

\*\*\*\*\*  
USACE / NAVFAC / AFCEA / NASA                      UFGS-23 09 23.13 20 (April 2007)  
-----  
Preparing Activity:    NAVFAC                      Replacing  
   UFGS-23 09 23.13 20 (January 2007)

## UNIFIED FACILITIES GUIDE SPECIFICATIONS

References are in agreement with UMRL dated January 2008

\*\*\*\*\*

### SECTION TABLE OF CONTENTS

#### DIVISION 23 - HEATING, VENTILATING, AND AIR CONDITIONING

#### SECTION 23 09 23.13 20

#### BACnet DIRECT DIGITAL CONTROL SYSTEMS FOR HVAC

04/07

#### PART 1    GENERAL

- 1.1    REFERENCES
- 1.2    DEFINITIONS
  - 1.2.1    ANSI/ASHRAE Standard 135
  - 1.2.2    ARCNET
  - 1.2.3    BACnet
  - 1.2.4    BACnet/IP
  - 1.2.5    BACnet Internetwork
  - 1.2.6    BACnet Network
  - 1.2.7    BACnet Segment
  - 1.2.8    BBMD
  - 1.2.9    BAS
  - 1.2.10    BAS Owner
  - 1.2.11    BIBBs
  - 1.2.12    BI
  - 1.2.13    BI/BTL
  - 1.2.14    Bridge
  - 1.2.15    Broadcast
  - 1.2.16    Device
  - 1.2.17    Device Object
  - 1.2.18    Device Profile
  - 1.2.19    Digital Controller
  - 1.2.20    Direct Digital Control (DDC)
  - 1.2.21    DDC System
  - 1.2.22    Ethernet
  - 1.2.23    Firmware
  - 1.2.24    Gateway
  - 1.2.25    Half Router
  - 1.2.26    Hub
  - 1.2.27    Internet Protocol (IP, TCP/IP, UDP/IP)
  - 1.2.28    Input/Output (I/O)
  - 1.2.29    I/O Expansion Unit
  - 1.2.30    IP subnet
  - 1.2.31    Local-Area Network (LAN)
  - 1.2.32    LonTalk

- 1.2.33 MAC Address
- 1.2.34 Master-Slave/Token-Passing (MS/TP)
- 1.2.35 Native BACnet Device
- 1.2.36 Network
- 1.2.37 Network Number
- 1.2.38 Object
- 1.2.39 Object Identifier
- 1.2.40 Object Properties
- 1.2.41 Peer-to-Peer
- 1.2.42 Performance Verification Test (PVT)
- 1.2.43 PID
- 1.2.44 PICS
- 1.2.45 Points
- 1.2.46 PTP
- 1.2.47 Repeater
- 1.2.48 Router
- 1.2.49 Stand-Alone Control
- 1.3 SUBCONTRACTOR SPECIAL REQUIREMENTS
- 1.4 BACnet DIRECT DIGITAL CONTROL SYSTEMS FOR HVAC DESCRIPTION
  - 1.4.1 Design Requirements
    - 1.4.1.1 Control System Drawings Title Sheet
    - 1.4.1.2 List of I/O Points
    - 1.4.1.3 Control System Components List
    - 1.4.1.4 Control System Schematics
    - 1.4.1.5 HVAC Equipment Electrical Ladder Diagrams
    - 1.4.1.6 Component Wiring Diagrams
    - 1.4.1.7 Terminal Strip Diagrams
    - 1.4.1.8 BACnet Communication Architecture Schematic
- 1.5 SUBMITTALS
- 1.6 QUALITY ASSURANCE
  - 1.6.1 Standard Products
  - 1.6.2 Delivery, Storage, and Handling
  - 1.6.3 Operating Environment
  - 1.6.4 Finish of New Equipment
  - 1.6.5 Verification of Dimensions
  - 1.6.6 Contractor's Qualifications
  - 1.6.7 Modification of References
  - 1.6.8 Project Sequence

## PART 2 PRODUCTS

- 2.1 DDC SYSTEM
  - 2.1.1 Direct Digital Controllers
    - 2.1.1.1 I/O Point Limitation
    - 2.1.1.2 Environmental Limits
    - 2.1.1.3 Stand-Alone Control
    - 2.1.1.4 Internal Clock
    - 2.1.1.5 Memory
    - 2.1.1.6 Immunity to Power Fluctuations
    - 2.1.1.7 Transformer
    - 2.1.1.8 Wiring Terminations
    - 2.1.1.9 Input and Output Interface
    - 2.1.1.10 Digital Controller BACnet Internetwork
    - 2.1.1.11 Communications Ports
    - 2.1.1.12 Modems
    - 2.1.1.13 BACnet Gateways
    - 2.1.1.14 Digital Controller Cabinet
    - 2.1.1.15 Main Power Switch and Receptacle
  - 2.1.2 DDC Software

- 2.1.2.1 Programming
- 2.1.2.2 Parameter Modification
- 2.1.2.3 Short Cycling Prevention
- 2.1.2.4 Equipment Status Delay
- 2.1.2.5 Run Time Accumulation
- 2.1.2.6 Timed Local Override
- 2.1.2.7 Time Synchronization
- 2.1.2.8 Scheduling
- 2.1.2.9 Object Property Override
- 2.1.2.10 Alarms and Events
- 2.1.2.11 Trending
- 2.1.2.12 Device Diagnostics
- 2.1.2.13 Power Loss
- 2.1.3 BACnet Operator Workstation
  - 2.1.3.1 BACnet Operator Workstation Hardware
  - 2.1.3.2 Password Protection
  - 2.1.3.3 BACnet Operator Workstation DDC Software
  - 2.1.3.4 Graphics Software
- 2.1.4 Notebook Computer
- 2.1.5 BACnet Protocol Analyzer
- 2.2 SENSORS AND INPUT HARDWARE
  - 2.2.1 Field-Installed Temperature Sensors
    - 2.2.1.1 Thermistors
    - 2.2.1.2 Resistance Temperature Detectors (RTDs)
    - 2.2.1.3 Temperature Sensor Details
  - 2.2.2 Transmitters
    - 2.2.2.1 Relative Humidity Transmitters
    - 2.2.2.2 Pressure Transmitters
  - 2.2.3 Current Transducers
  - 2.2.4 Pneumatic to Electric Transducers
  - 2.2.5 Air Quality Sensors
    - 2.2.5.1 CO2 Sensors
    - 2.2.5.2 Air Quality Sensors
  - 2.2.6 Input Switches
    - 2.2.6.1 Timed Local Overrides
  - 2.2.7 Freeze Protection Thermostats
  - 2.2.8 Air Flow Measurement Stations
  - 2.2.9 Energy Metering
    - 2.2.9.1 Electric Meters
    - 2.2.9.2 Steam Meters
- 2.3 OUTPUT HARDWARE
  - 2.3.1 Control Dampers
  - 2.3.2 Control Valves
    - 2.3.2.1 Valve Assembly
    - 2.3.2.2 Butterfly Valves
    - 2.3.2.3 Two-Way Valves
    - 2.3.2.4 Three-Way Valves
    - 2.3.2.5 Valves for Chilled Water, Condenser Water, and Glycol Fluid Service
    - 2.3.2.6 Valves for Hot Water Service
    - 2.3.2.7 Valves for High Temperature Hot Water Service
    - 2.3.2.8 Valves for Steam Service
  - 2.3.3 Actuators
    - 2.3.3.1 Electric Actuators
    - 2.3.3.2 Pneumatic Actuators
  - 2.3.4 Output Signal Conversion
    - 2.3.4.1 Electronic-to-Pneumatic Transducers
  - 2.3.5 Output Switches
    - 2.3.5.1 Control Relays

- 2.4 ELECTRICAL POWER AND DISTRIBUTION
  - 2.4.1 Transformers
  - 2.4.2 Surge and Transient Protection
    - 2.4.2.1 Power Line Surge Protection
    - 2.4.2.2 Telephone and Communication Line Surge Protection
    - 2.4.2.3 Controller Input/Output Protection
  - 2.4.3 Wiring
    - 2.4.3.1 Power Wiring
    - 2.4.3.2 Analog Signal Wiring
- 2.5 FIRE PROTECTION DEVICES
  - 2.5.1 Duct Smoke Detectors
- 2.6 INDICATORS
  - 2.6.1 Thermometers
  - 2.6.2 Pressure Gauges for Piping Systems
  - 2.6.3 Pressure Gauges for Pneumatic Controls
- 2.7 PNEUMATIC POWER SUPPLY AND TUBING
  - 2.7.1 Air Compressors
    - 2.7.1.1 Compressed Air Tank
  - 2.7.2 Refrigerated Air Dryers
  - 2.7.3 Compressed Air Discharge Filters
  - 2.7.4 Air Pressure-Reducing Stations
  - 2.7.5 In-line Filters
  - 2.7.6 Pneumatic Tubing
    - 2.7.6.1 Copper Tubing
    - 2.7.6.2 Polyethylene Tubing
- 2.8 VARIABLE FREQUENCY (MOTOR) DRIVES
  - 2.8.1 VFD Quality Assurance
  - 2.8.2 VFD Service Support
  - 2.8.3 VFD Features
  - 2.8.4 Programmable Parameters
  - 2.8.5 Protective Features
  - 2.8.6 Minimum Operating Conditions
  - 2.8.7 Additional Features

## PART 3 EXECUTION

- 3.1 INSTALLATION
  - 3.1.1 BACnet Naming and Addressing
  - 3.1.2 Minimum BACnet Object Requirements
  - 3.1.3 Minimum BACnet Service Requirements
  - 3.1.4 Local Area Networks
  - 3.1.5 BACnet Routers, Bridges, and Switches
  - 3.1.6 Wiring Criteria
  - 3.1.7 Accessibility
  - 3.1.8 Digital Controllers
  - 3.1.9 Hand-Off-Auto Switches
  - 3.1.10 Temperature Sensors
    - 3.1.10.1 Room Temperature Sensors
    - 3.1.10.2 Duct Temperature Sensors
    - 3.1.10.3 Immersion Temperature Sensors
    - 3.1.10.4 Outside Air Temperature Sensors
  - 3.1.11 Energy Meters
  - 3.1.12 Damper Actuators
  - 3.1.13 Thermometers and Gages
  - 3.1.14 Pressure Sensors
  - 3.1.15 Pneumatic Tubing
  - 3.1.16 Component Identification Labeling
  - 3.1.17 Network and Telephone Communication Lines
- 3.2 TEST AND BALANCE SUPPORT

3.3	CONTROLS SYSTEM OPERATORS MANUALS
3.3.1	Storage Cabinets
3.4	PERFORMANCE VERIFICATION TESTING (PVT)
3.4.1	General
3.4.2	Performance Verification Testing Plan
3.4.3	PVT Sample Size
3.4.4	Pre-Performance Verification Testing Checklist
3.4.5	Conducting Performance Verification Testing
3.4.6	Controller Capability and Labeling
3.4.7	Workstation and Software Operation
3.4.8	BACnet Communications and Interoperability Areas
3.4.9	Execution of Sequence of Operation
3.4.10	Control Loop Stability and Accuracy
3.4.11	Performance Verification Testing Report
3.5	TRAINING REQUIREMENTS
3.5.1	Training Documentation
3.5.2	Phase I Training - Fundamentals
3.5.3	Phase II Training - Operation
-- End of Section Table of Contents --	

\*\*\*\*\*  
USACE / NAVFAC / AFCEA / NASA           UFGS-23 09 23.13 20 (April 2007)  
-----  
Preparing Activity:   NAVFAC           Replacing  
  UFGS-23 09 23.13 20 (January 2007)

## UNIFIED FACILITIES GUIDE SPECIFICATIONS

References are in agreement with UMRL dated January 2008

\*\*\*\*\*

### SECTION 23 09 23.13 20

#### BACnet DIRECT DIGITAL CONTROL SYSTEMS FOR HVAC 04/07

\*\*\*\*\*

NOTE: This guide specification covers the Navy requirements for direct digital control (DDC) of heating, ventilating, and air conditioning (HVAC) systems complying with ANSI/ASHRAE Standard 135-2004, "BACnet - A Data Communication Protocol for Building Automation and Control Networks." BACnet is also an international standard, ISO 16484-5. The intent of this specification is for the DDC system to communicate using the BACnet standard.

This specification is not for use in USACE projects.

The control system will have a BACnet interface for connection to a hand-held device, portable computer, and/or a central workstation computer. Interface computers allow an operator to view operational status, enable and disable equipment, change setpoints, set schedules, receive trends and alarms, and allow storage, modification and downloading of control programming. The operator workstation can be located in the building (directly connected) or at a remote site (connected via a LAN or modem).

If you have questions about the design of direct digital control systems, contact Facilities Engineering Command (FEC) Regional Mechanical Engineer, Naval Facilities Engineering Command Atlantic Mechanical Engineering, or the Naval Facilities Engineering Service Center (NFESC), Code 223.

Edit this guide specification for project specific requirements by adding, deleting, or revising text. For bracketed items, choose applicable items(s) or insert appropriate information.

Remove information and requirements not required in respective project, whether or not brackets are present.

Comments and suggestions on this guide specification are welcome and should be directed to the technical proponent of the specification. A listing of technical proponents, including their organization designation and telephone number, is on the Internet.

Recommended changes to a UFGS should be submitted as a Criteria Change Request (CCR).

\*\*\*\*\*

\*\*\*\*\*

NOTE: This specification requires the new DDC system to support ASHRAE 135 at all device and network levels. If a legacy DDC system is already installed at the building, and costs are too high for replacement, the legacy devices may require a gateway to connect the legacy network/devices to the BACnet architecture. Indicate on the drawings where gateways are required.

\*\*\*\*\*

\*\*\*\*\*

NOTE: Avoid using pneumatic powered controls in new DDC systems. In existing systems, replace pneumatic controls with electric/electronic controls when possible.

\*\*\*\*\*

## PART 1 GENERAL

### 1.1 REFERENCES

\*\*\*\*\*

NOTE: This paragraph is used to list the publications cited in the text of the guide specification. The publications are referred to in the text by basic designation only and listed in this paragraph by organization, designation, date, and title.

Use the Reference Wizard's Check Reference feature when you add a RID outside to the Section's Reference Article to automatically place the reference in the Reference Article. Also use the Reference Wizard's Check Reference feature to update the issue dates.

References not used in the text will automatically be deleted from this section of the project specification when you choose to reconcile references in the publish print process.

\*\*\*\*\*

The publications listed below form a part of this specification to the extent referenced. The publications are referred to in the text by the basic designation only.

AIR MOVEMENT AND CONTROL ASSOCIATION INTERNATIONAL (AMCA)

AMCA 500-D (1998) Laboratory Methods of Testing  
Dampers for Rating

AMERICAN NATIONAL STANDARDS INSTITUTE (ANSI)

ANSI/ATA 878.1 (1999) ARCNET - Local Area Network: Token  
Ring

AMERICAN SOCIETY OF HEATING, REFRIGERATING AND AIR-CONDITIONING  
ENGINEERS (ASHRAE)

ASHRAE 135 (2004; Interpretations 1 thru 18; Addenda  
A 2004; Errata 2005; Addenda C 2006;  
Addenda D 2006; Errata to Addenda D 2006;  
Addenda F 2007; Addenda E 2007; Errata  
2007) BACnet

ASME INTERNATIONAL (ASME)

ASME B16.18 (2001; R 2005) Cast Copper Alloy Solder  
Joint Pressure Fittings

ASME B16.22 (2001; R 2005) Standard for Wrought Copper  
and Copper Alloy Solder Joint Pressure  
Fittings

ASME B16.26 (2006) Standard for Cast Copper Alloy  
Fittings for Flared Copper Tubes

ASME B16.34 (2004) Valves - Flanged, Threaded and  
Welding End

ASME B16.5 (2003) Standard for Pipe Flanges and  
Flanged Fittings: NPS 1/2 Through NPS 24

ASME B31.1 (2004; Addenda A 2005; Addenda B 2006)  
Power Piping

ASME B40.100 (2006) Pressure Gauges and Gauge  
Attachments

ASME BPVC (2007) Boiler and Pressure Vessel Codes

ASTM INTERNATIONAL (ASTM)

ASTM A 126 (2004) Standard Specification for Gray  
Iron Castings for Valves, Flanges, and  
Pipe Fittings

ASTM B 117 (2007) Standard Practice for Operating  
Salt Spray (Fog) Apparatus

ASTM B 32 (2004) Standard Specification for Solder  
Metal

ASTM B 75 (2002) Standard Specification for Seamless  
Copper Tube



ASTM B 88	(2003) Standard Specification for Seamless Copper Water Tube
ASTM B 88M	(2005) Standard Specification for Seamless Copper Water Tube (Metric)
ASTM D 1238	(2004c) Melt Flow Rates of Thermoplastics by Extrusion Plastometer
ASTM D 1693	(2007) Standard Test Method for Environmental Stress-Cracking of Ethylene Plastics
ASTM D 635	(2006) Standard Test Method for Rate of Burning and/or Extent and Time of Burning of Self-Supporting Plastics in a Horizontal Position
ASTM D 638	(2003) Standard Test Method for Tensile Properties of Plastics
ASTM D 792	(2000) Density and Specific Gravity (Relative Density) of Plastics by Displacement

#### INSTITUTE OF ELECTRICAL AND ELECTRONICS ENGINEERS (IEEE)

IEEE C57.13	(1993; R 2003) Standard Requirements for Instrument Transformers
IEEE C62.41.1	(2002) IEEE Guide on the Surges Environment in Low-Voltage (1000 V and Less) AC Power Circuits
IEEE C62.41.2	(2002) IEEE Recommended Practice on Characterization of Surges in Low-Voltage (1000 V and Less) AC Power Circuits
IEEE C62.45	(2002) Surge Testing for Equipment Connected to Low-Voltage (1000v and less)AC Power Circuits

#### INTERNATIONAL ORGANIZATION FOR STANDARDIZATION (ISO)

ISO/IEC 8802	(2000) Telecommunications and Information Exchange Between Systems
--------------	--

#### NATIONAL FIRE PROTECTION ASSOCIATION (NFPA)

NFPA 70	(2007) National Electrical Code
NFPA 72	(2006) National Fire Alarm Code
NFPA 90A	(2002; Errata 2003; Errata 2005) Standard for the Installation of Air Conditioning and Ventilating Systems

NATIONAL FLUID POWER ASSOCIATION (NFLPA)

NFLPA C12.10 (2004) Watthour Meters

SHEET METAL AND AIR CONDITIONING CONTRACTORS' NATIONAL ASSOCIATION  
(SMACNA)

SMACNA HVAC Duct Const Stds (1995; Addendum 1997, 2nd Ed) HVAC Duct  
Construction Standards - Metal and Flexible

UNDERWRITERS LABORATORIES (UL)

UL 1449 (2006) Surge Protective Devices

UL 506 (2000; Rev thru May 2006) Standard for  
Specialty Transformers

UL 508A (2001; Rev thru Sep 2005) Standard for  
Industrial Control Panels

UL 916 (1998; Rev thru Mar 2006) Energy  
Management Equipment

1.2 DEFINITIONS

1.2.1 ANSI/ASHRAE Standard 135

ANSI/ASHRAE Standard 135: BACnet - A Data Communication Protocol for Building Automation and Control Networks, referred to as "BACnet". ASHRAE developed BACnet to provide a method for diverse building automation devices to communicate and share data over a network.

1.2.2 ARCNET

ANSI/ATA 878.1 - Attached Resource Computer Network. ARCNET is a deterministic LAN technology; meaning it's possible to determine the maximum delay before a device is able to transmit a message.

1.2.3 BACnet

Building Automation and Control Network; the common name for the communication standard ASHRAE 135. The standard defines methods and protocol for cooperating building automation devices to communicate over a variety of LAN technologies.

1.2.4 BACnet/IP

An extension of BACnet, Annex J, defines this mechanism using a reserved UDP socket to transmit BACnet messages over IP networks. A BACnet/IP network is a collection of one or more IP subnetworks that share the same BACnet network number. See also "BACnet Broadcast Management Device".

1.2.5 BACnet Internetwork

Two or more BACnet networks, possibly using different LAN technologies, connected with routers. In a BACnet internetwork, there exists only one message path between devices.

#### 1.2.6 BACnet Network

One or more BACnet segments that have the same network address and are interconnected by bridges at the physical and data link layers.

#### 1.2.7 BACnet Segment

One or more physical segments of BACnet devices on a BACnet network, connected at the physical layer by repeaters.

#### 1.2.8 BBMD

BACnet Broadcast Management Device (BBMD). A communications device, typically combined with a BACnet router. A BBMD forwards BACnet broadcast messages to BACnet/IP devices and other BBMDs connected to the same BACnet/IP network. Every IP subnetwork that is part of a BACnet/IP network must have only one BBMD. See also "BACnet/IP".

#### 1.2.9 BAS

Building Automation Systems, including DDC (Direct Digital Controls) used for facility automation and energy management.

\*\*\*\*\*  
**NOTE: Identify the BAS Owner early in project development. Include the BAS Owner in the project team responsible for design, solicitation, construction, and final acceptance.**  
\*\*\*\*\*

#### 1.2.10 BAS Owner

The regional or local user responsible for managing all aspects of the BAS operation, including: network connections, workstation management, submittal review, technical support, control parameters, and daily operation. The BAS Owner for this project is [\_\_\_\_\_].

#### 1.2.11 BIBBs

BACnet Interoperability Building Blocks. A collection of BACnet services used to describe supported tasks. BIBBs are often described in terms of "A" (client) and "B" (server) devices. The "A" device uses data provided by the "B" device, or requests an action from the "B" device.

#### 1.2.12 BI

BACnet International, formerly two organizations: the BACnet Manufacturers Association (BMA) and the BACnet Interest Group - North America (BIG-NA).

#### 1.2.13 BI/BTL

BACnet International/BACnet Testing Laboratories (Formerly BMA/BTL). The organization responsible for testing products for compliance with the BACnet standard, operated under the direction of BACnet International.

#### 1.2.14 Bridge

Network hardware that connects two or more network (or BACnet internetwork) segments at the physical and data link layers. A bridge may also filter

messages.

#### 1.2.15 Broadcast

A message sent to all devices on a network segment.

#### 1.2.16 Device

Any control system component, usually a digital controller, that contains a BACnet Device Object and uses BACnet to communicate with other devices. See also "Digital Controller".

#### 1.2.17 Device Object

Every BACnet device requires one Device Object, whose properties represent the network visible properties of that device. Every Device Object requires a unique Object Identifier number on the BACnet internetwork. This number is often referred to as the device instance.

#### 1.2.18 Device Profile

A collection of BIBBs determining minimum BACnet capabilities of a device, defined in ASHRAE Standard 135-2004, Annex L. Standard device profiles include BACnet Operator Workstations (B-OWS), BACnet Building Controllers (B-BC), BACnet Advanced Application Controllers (B-AAC), BACnet Application Specific Controllers (B-ASC), BACnet Smart Actuator (B-SA), and BACnet Smart Sensor (B-SS). Each device used in new construction is required to have a PICS statement listing BIBBs supported.

#### 1.2.19 Digital Controller

An electronic controller, usually with internal programming logic and digital and analog input/output capability, which performs control functions. In most cases, synonymous with a BACnet device described in this specification. See also "Device".

#### 1.2.20 Direct Digital Control (DDC)

Digital controllers performing control logic. Usually the controller directly senses physical values, makes control decisions with internal programs, and outputs control signals to directly operate switches, valves, dampers, and motor controllers.

#### 1.2.21 DDC System

A network of digital controllers, communication architecture, and user interfaces. A DDC system may include programming, sensors, actuators, switches, relays, factory controls, operator workstations, and various other devices, components, and attributes.

#### 1.2.22 Ethernet

A family of local-area-network technologies providing high-speed networking features over various media.

#### 1.2.23 Firmware

Software programmed into read only memory (ROM), flash memory, electrically erasable programmable read only memory (EEPROM), or erasable programmable

read only memory (EPROM) chips.

#### 1.2.24 Gateway

Communication hardware connecting two or more different protocols, similar to human language translators. The Gateway translates one protocol into equivalent concepts for the other protocol. In BACnet applications, a gateway has BACnet on one side and non-BACnet (usually proprietary) protocols on the other side.

#### 1.2.25 Half Router

A device that participates as one partner in a BACnet point-to-point (PTP) connection. Two half-routers in an active PTP connection combine to form a single router.

#### 1.2.26 Hub

A common connection point for devices on a network.

#### 1.2.27 Internet Protocol (IP, TCP/IP, UDP/IP)

A communication method, the most common use is the World Wide Web. At the lowest level, it is based on Internet Protocol (IP), a method for conveying and routing packets of information over various LAN media. Two common protocols using IP are User Datagram Protocol (UDP) and Transmission Control Protocol (TCP). UDP conveys information to well-known "sockets" without confirmation of receipt. TCP establishes "sessions", which have end-to-end confirmation and guaranteed sequence of delivery.

#### 1.2.28 Input/Output (I/O)

Physical inputs and outputs to and from a device, although the term sometimes describes software, or "virtual" I/O. See also "Points".

#### 1.2.29 I/O Expansion Unit

An I/O expansion unit provides additional point capacity to a digital controller.

#### 1.2.30 IP subnet

Internet protocol (IP) identifies individual devices with a 32-bit number divided into four groups from 0 to 255. Devices are often grouped and share some portion of this number. For example, one device has IP address 209.185.47.68 and another device has IP address 209.185.47.82. These two devices share Class C subnet 209.185.47.00

#### 1.2.31 Local-Area Network (LAN)

A communication network that spans a limited geographic area and uses the same basic communication technology throughout.

#### 1.2.32 LonTalk

ANSI/EIA 709. A communication protocol developed by Echelon Corp. LonTalk is an optional physical and data link layer for BACnet.

#### 1.2.33 MAC Address

Media Access Control address. The physical node address that identifies a device on a Local Area Network.

#### 1.2.34 Master-Slave/Token-Passing (MS/TP)

ISO/IEC 8802 (Part 3). One of the LAN options for BACnet. MSTP uses twisted-pair wiring for relatively low speed and low cost communication (up to 4,000 ft at 76.8K bps).

#### 1.2.35 Native BACnet Device

A device that uses BACnet as its primary, if not only, method of communication with other BACnet devices without intermediary gateways. A system that uses native BACnet devices at all levels is a native BACnet system.

#### 1.2.36 Network

Communication technology for data communications. BACnet approved network types are BACnet over Internet Protocol (IP), Point to Point (PTP) Ethernet, ARCNET, MS/TP, and LonTalk®.

#### 1.2.37 Network Number

A site-specific number assigned to each network segment to identify for routing. This network number must be unique throughout the BACnet internetwork.

#### 1.2.38 Object

The concept of organizing BACnet information into standard components with various associated properties. Examples include analog input objects and binary output objects.

#### 1.2.39 Object Identifier

An object property used to identify the object, including object type and instance. Object Identifiers must be unique within a device.

#### 1.2.40 Object Properties

Attributes of an object. Examples include present value and high limit properties of an analog input object. Properties are defined in ASHRAE 135; some are optional and some are required. Objects are controlled by reading from and writing to object properties.

#### 1.2.41 Peer-to-Peer

Peer-to-peer refers to devices where any device can initiate and respond to communication with other devices.

#### 1.2.42 Performance Verification Test (PVT)

The procedure for determining if the installed BAS meets design criteria prior to final acceptance. The PVT is performed after installation, testing, and balancing of mechanical systems. Typically the PVT is performed by the Contractor in the presence of the Government.

#### 1.2.43 PID

Proportional, integral, and derivative control; three parameters used to control modulating equipment to maintain a setpoint. Derivative control is often not required for HVAC systems (leaving "PI" control).

#### 1.2.44 PICS

Protocol Implementation Conformance Statement (PICS), describing the BACnet capabilities of a device. See BACnet, Annex A for the standard format and content of a PICS statement.

#### 1.2.45 Points

Physical and virtual inputs and outputs. See also "Input/Output".

#### 1.2.46 PTP

Point-to-Point protocol connects individual BACnet devices or networks using serial connections like modem-to-modem links.

#### 1.2.47 Repeater

A network component that connects two or more physical segments at the physical layer.

#### 1.2.48 Router

A BACnet router is a component that joins together two or more networks using different LAN technologies. Examples include joining a BACnet Ethernet LAN to a BACnet MS/TP LAN.

#### 1.2.49 Stand-Alone Control

Refers to devices performing equipment-specific and small system control without communication to other devices or computers for physical I/O, excluding outside air and other common shared conditions. Devices are located near controlled equipment, with physical input and output points limited to 64 or less per device, except for complex individual equipment or systems. Failure of any single device will not cause other network devices to fail. BACnet "Smart" actuators (B-SA profile) and sensors (B-SS profile) communicating on a network with a parent device are exempt from stand-alone requirements.

### [1.3 SUBCONTRACTOR SPECIAL REQUIREMENTS

\*\*\*\*\*

**NOTE: Delete this paragraph when using this section  
for a design-build project specification. This  
requirement is covered by the specifications in  
NAVFAC Design-Build RFP PART 4, Section D30 HVAC**

\*\*\*\*\*  
Perform all work in this section in accordance with the paragraph entitled "Subcontractor Special Requirements" in Section 01 30 00 ADMINISTRATIVE REQUIREMENTS. The paragraph specifies that all contract requirements of this section shall be accomplished directly by a first tier subcontractor. No work required shall be accomplished by a second tier subcontractor.]

#### 1.4 BACnet DIRECT DIGITAL CONTROL SYSTEMS FOR HVAC DESCRIPTION

\*\*\*\*\*

NOTE: A thorough investigation of existing systems, hardware, and BAS Owner needs is required before modifying the DDC system description below. You must describe what new DDC equipment goes into the building(s), what are the computer\operator interface requirements, and how the new controls and operator interface will interact with existing infrastructure. System architecture diagrams are very helpful at this point.

\*\*\*\*\*

- a. [Remove existing and] [provide new BACnet] [and] [modify existing] [and merge with existing non-BACnet] [and merge with existing BACnet] DDC systems including associated equipment and accessories. All new devices are accessible using a Web browser interface and communicate using ASHRAE 135 BACnet communications without the use of gateways, unless gateways are shown on the design drawings and specifically requested by the Government. Where gateways are allowed, they must support ASHRAE 135, including all object properties and read-write services shown on Government approved interoperability schedules. Manufacturer's products, including design, materials, fabrication, assembly, inspection, and testing shall be in accordance with **ASHRAE 135**, **ASME B31.1**, and **NFPA 70**, except where indicated otherwise.

\*\*\*\*\*

NOTE: The next paragraph provides more specific information when merging or adding a new to existing BACnet system.

\*\*\*\*\*

- [b. The existing DDC system is manufactured by [ ]. The server and operator workstation are located at [ ]. If installing a system made by the same manufacturer, upgrade or replace the existing server, operator workstation, and laptop computer software with the manufacturer's latest software version for all used applications. Upgrade hardware, memory, and operating systems if required.]

##### 1.4.1 Design Requirements

###### 1.4.1.1 Control System Drawings Title Sheet

Provide a title sheet for the control system drawing set. Include the project title, project location, contract number, the controls contractor preparing the drawings, an index of the control drawings in the set, and a legend of the symbols and abbreviations used throughout the control system drawings.

###### 1.4.1.2 List of I/O Points

Also known as a Point Schedule, provide for each input and output point physically connected to a digital controller: point name, point description, point type (Analog Output (AO), Analog Input (AI), Binary Output (BO), Binary Input (BI)), point sensor range, point actuator range, point address, BACnet object, associated BIBBS (where applicable), and



point connection terminal number. Typical schedules for multiple identical equipment are allowed unless otherwise requested in design or contract criteria.

#### 1.4.1.3 Control System Components List

Provide a complete list of control system components installed on this project. Include for each controller and device: control system schematic name, control system schematic designation, device description, manufacturer, and manufacturer part number. For sensors, include point name, sensor range, and operating limits. For valves, include body style, Cv, design flow rate, pressure drop, valve characteristic (linear or equal percentage), and pipe connection size. For actuators, include point name, spring or non-spring return, modulating or two-position action, normal (power fail) position, nominal control signal operating range (0-10 volts DC or 4-20 milliamps), and operating limits.

#### 1.4.1.4 Control System Schematics

Provide control system schematics. Typical schematics for multiple identical equipment are allowed unless otherwise requested in design or contract criteria. Include the following:

- a. Location of each input and output device
- b. Flow diagram for each piece of HVAC equipment
- c. Name or symbol for each control system component, such as V-1 for a valve
- d. Setpoints, with differential or proportional band values
- e. Written sequence of operation for the HVAC equipment
- f. Valve and Damper Schedules, with normal (power fail) position

#### 1.4.1.5 HVAC Equipment Electrical Ladder Diagrams

Provide HVAC equipment electrical ladder diagrams. Indicate required electrical interlocks.

#### 1.4.1.6 Component Wiring Diagrams

Provide a wiring diagram for each type of input device and output device. Indicate how each device is wired and powered; showing typical connections at the digital controller and power supply. Show for all field connected devices such as control relays, motor starters, actuators, sensors, and transmitters.

#### 1.4.1.7 Terminal Strip Diagrams

Provide a diagram of each terminal strip. Indicate the terminal strip location, termination numbers, and associated point names.

#### 1.4.1.8 BACnet Communication Architecture Schematic

Provide a schematic showing the project's entire BACnet communication network, including addressing used for LANs, LAN devices including routers and bridges, gateways, controllers, workstations, and field interface

devices. If applicable, show connection to existing networks.

#### 1.5 SUBMITTALS

Submit detailed and annotated manufacturer's data, drawings, and specification sheets for each item listed, that clearly show compliance with the project specifications.

Government approval is required for submittals with a "G" designation; submittals not having a "G" designation are for Contractor Quality Control approval. Submit the following according to 01 33 00 SUBMITTAL PROCEDURES:

\*\*\*\*\*  
NOTE: The BAS Owner will be the primary reviewer  
for submittals marked by the "G". Delete items if  
not used in the control system.  
\*\*\*\*\*

##### SD-02 Shop Drawings

Include the following in the project's control system drawing set:

Control system drawings title sheet; G  
List of I/O Points; G  
Control System Components List; G  
Control system schematics; G  
HVAC Equipment Electrical Ladder diagrams; G  
Component wiring diagrams; G  
Terminal strip diagrams; G  
BACnet communication architecture schematic; G

##### SD-03 Product Data

Direct Digital Controllers; G

Include BACnet PICS for each controller/device type, including smart sensors (B-SS) and smart actuators (B-SA).

BACnet Gateways; G

Include BACnet and workstation display information; bi-directional communication ability; compliance with interoperability schedule; expansion capacity; handling of alarms, events, scheduling and trend data; and single device capability (not depending on multiple devices for exchanging information from either side of the gateway).

BACnet Protocol Analyzer; G

Include capability to store and report data traffic on BACnet networks, measure bandwidth usage, filter information, and identify BACnet devices.

DDC Software; G

BACnet Operator Workstation; G

BACnet Operator Workstation DDC Software; G

Include BACnet PICS for Operator Workstation software.

Notebook Computer; G

Sensors and Input Hardware; G

Output Hardware; G

Surge and transient protection; G

Indicators; G

[Air compressors; G]

[Refrigerated air dryers; G]

[Pneumatic tubing; G]

\*\*\*\*\*  
NOTE: Delete this item if smoke detectors are furnished under Section  
13852N, "Interior Fire Detection and Alarm System."  
\*\*\*\*\*

[Duct smoke detectors; G]

\*\*\*\*\*  
NOTE: Delete this item if VFDs are furnished under another section.  
\*\*\*\*\*

[Variable frequency (motor) drives; G]

#### SD-05 Design Data

Performance Verification Testing Plan; G

Pre-Performance Verification Testing Checklist; G

#### SD-06 Test Reports

Performance Verification Testing Report; G

#### SD-07 Certificates

Contractor's Qualifications; G

#### SD-09 Manufacturer's Field Reports

Pre-PVT Checklist; G

#### SD-10 Operation and Maintenance Data

Comply with requirements for data packages in Section 01 78 23  
OPERATION AND MAINTENANCE DATA, except as supplemented and  
modified in this specification.

BACnet Direct Digital Control Systems, Data Package 4; G

Controls System Operators Manuals, Data Package 4; G

VFD Service Manuals, Data Package 4; G

#### SD-11 Closeout Submittals

Training documentation; G

### 1.6 QUALITY ASSURANCE

#### 1.6.1 Standard Products

Provide material and equipment that are standard manufacturer's products currently in production and supported by a local service organization.

#### 1.6.2 Delivery, Storage, and Handling

Handle, store, and protect equipment and materials to prevent damage before and during installation according to manufacturer's recommendations, and as approved by the Contracting Officer. Replace damaged or defective items.

#### 1.6.3 Operating Environment

Protect components from humidity and temperature variation, dust, and contaminants. If components are stored before installation, keep them within the manufacturer's limits.

#### 1.6.4 Finish of New Equipment

New equipment finishing shall be factory provided. Manufacturer's standard factory finishing shall be proven to withstand 125 hours in a salt-spray fog test. Equipment located outdoors shall be proven to withstand 500 hours in a salt-spray fog test.

Salt-spray fog test shall be according to [ASTM B 117](#), with acceptance criteria as follows: immediately after completion of the test, the finish shall show no signs of degradation or loss of adhesion beyond [0.125 inch](#) on either side of the scratch mark.

#### 1.6.5 Verification of Dimensions

The contractor shall verify all dimensions in the field, and advise the Contracting Officer of any discrepancy before performing work.

#### 1.6.6 Contractor's Qualifications

Submit documentation certifying the controls Contractor performing the work has completed at least three DDC systems installations of a similar design to this project, and programmed similar sequences of operation for at least two years.

#### 1.6.7 Modification of References

The advisory provisions in [ASME B31.1](#) and [NFPA 70](#) are mandatory. Substitute "shall" for "should" wherever it appears and interpret all references to the "authority having jurisdiction" and "owner" to mean the

Contracting Officer.

#### 1.6.8 Project Sequence

The control system work for this project shall proceed in the following order:

- a. Submit and receive approval on the Shop Drawings, Product Data, and Certificates specified under the paragraph entitled "SUBMITTALS."
- b. Perform the control system installation work, including all field check-outs and tuning.
- c. Provide support to TAB personnel as specified under the paragraph "TEST AND BALANCE SUPPORT."
- d. Submit and receive approval of the Controls System Operators Manual specified under the paragraph "CONTROLS SYSTEM OPERATORS MANUALS."
- e. Submit and receive approval of the Performance Verification Testing Plan and the Pre-PVT Checklist specified under the paragraph "PERFORMANCE VERIFICATION TESTING."
- f. Perform the Performance Verification Testing.
- g. Submit and receive approval on the PVT Report.
- h. Submit and receive approval on the Training Documentation specified under the paragraph "INSTRUCTION TO GOVERNMENT PERSONNEL"[ and "VFD Service Support"]. Submit at least 30 days before training.
- i. Deliver the final Controls System Operators Manuals[ and VFD Service Manuals].
- j. Conduct the Phase I Training[ and VFD on-site/hands-on training].
- k. Conduct the Phase II Training.
- l. Submit and receive approval of Closeout Submittals.

### PART 2 PRODUCTS

#### 2.1 DDC SYSTEM

\*\*\*\*\*

NOTE: Consider below whether to require integral, or factory-provided ("Native") BACnet controllers for HVAC and plant equipment. If so, coordinate this requirement with other sections and specifications for plant equipment. This allows eliminating redundant sensor/actuator requirements and provides access to many control and status parameters using BACnet with a single LAN connection to the equipment. Possible disadvantages include higher cost, disqualifying otherwise qualified vendors, and more detailed integration criteria.

\*\*\*\*\*

\*\*\*\*\*

NOTE: Using only BTL listed devices (last sentence in brackets paragraph 2.1.a) requires investigation. Devices listed by the BACnet Testing Labs will provide a higher level of assurance that they meet claimed performance. However, requiring BTL listed products may eliminate otherwise qualified vendors, or those in line for testing but not yet certified. To help determine whether this requirement should be used, a current list of BTL certified devices are published at:  
<http://bacnetassociation.org/btl/>.

\*\*\*\*\*

- a. Provide a networked DDC system for stand-alone control in compliance with the latest revision of the **ASHRAE 135** BACnet standard. Include all programming, objects, and services required to meet the sequence of control. Provide BACnet communications between the DDC system and native BACnet devices furnished with HVAC equipment [and plant equipment including boilers, chillers, and variable frequency drives]. [Devices provided shall be certified in the BACnet Testing Laboratories (BTL) Product Listing.]

\*\*\*\*\*

NOTE: Always indicate the location of operator workstations and servers on project drawings. Edit and coordinate the below paragraph with Section 1, DDC System Description and the BAS Owner.

\*\*\*\*\*

- [b. Provide an operator workstation [and new server] with complete interface software capable of programming, configuring, and monitoring the digital controllers.] [Interface the new DDC system with the site's existing server and operator workstation and software including graphic creation, scheduling, alarming, and trending. The server and workstation are located at \_\_\_\_\_]

#### 2.1.1.1 Direct Digital Controllers

Direct digital controllers shall be **UL 916** rated.

##### 2.1.1.1.1 I/O Point Limitation

The total number of I/O hardware points used by a single stand-alone digital controller, including I/O expansion units, shall not exceed 64, except for complex individual equipment or systems. Place I/O expansion units in the same cabinet as the digital controller.

##### 2.1.1.1.2 Environmental Limits

Controllers shall be suitable for, or placed in protective enclosures suitable for the environment (temperature, humidity, dust, and vibration) where they are located.

#### 2.1.1.3 Stand-Alone Control

Provide stand-alone digital controllers.

#### 2.1.1.4 Internal Clock

Provide internal clocks for all BACnet Building Controllers (B-BC) and BACnet Advanced Application Controllers (B-AAC) using BACnet time synchronization services. Automatically synchronize system clocks daily from an operator-designated controller. The system shall automatically adjust for daylight saving time.

#### 2.1.1.5 Memory

Provide sufficient memory for each controller to support the required control, communication, trends, alarms, and messages. Protect programs residing in memory with EEPROM, flash memory, or by an uninterruptible power source (battery or uninterruptible power supply). The backup power source shall have capacity to maintain the memory during a 72-hour continuous power outage. Rechargeable power sources shall be constantly charged while the controller is operating under normal line power. Batteries shall be replaceable without soldering. Trend and alarm history collected during normal operation shall not be lost during power outages less than 72 hours long.

#### 2.1.1.6 Immunity to Power Fluctuations

Controllers shall operate at 90% to 110% nominal voltage rating.

#### 2.1.1.7 Transformer

The controller power supply shall be fused or current limiting and rated at 125% power consumption.

#### 2.1.1.8 Wiring Terminations

Use screw terminal wiring terminations for all field-installed controllers. Provide field-removable modular terminal strip or a termination card connected by a ribbon cable for all controllers other than terminal units.

#### 2.1.1.9 Input and Output Interface

Provide hard-wired input and output interface for all controllers as follows:

- a. Protection: Shorting an input or output point to itself, to another point, or to ground shall cause no controller damage. Input or output point contact with sources up to 24 volts AC or DC for any duration shall cause no controller damage.
- b. Binary Inputs: Binary inputs shall have a toggle switch and monitor on and off contacts from a "dry" remote device without external power, and external 5-24 VDC voltage inputs.
- c. Pulse Accumulation Inputs: Pulse accumulation inputs shall conform to binary input requirements and accumulate pulses at a resolution suitable to the application.

- d. Analog Inputs: Analog inputs shall monitor low-voltage (0-10 VDC), current (4-20 mA), or resistance (thermistor or RTD) signals.
- e. Binary Outputs: Binary outputs shall have a toggle switch and send a pulsed 24 VDC low-voltage signal for modulation control, or provide a maintained open-closed position for on-off control. For HVAC equipment and plant controllers, provide for manual overrides, either with three-position (on-off-auto) override switches and status lights, or with an adjacent operator display and interface. Where appropriate, provide a method to select normally open or normally closed operation.
- f. Analog Outputs: Analog outputs shall send modulating 0-10 VDC or 4-20 mA signals to control output devices.
- g. Tri-State Outputs: Tri-State outputs shall provide three-point floating control of terminal unit electronic actuators.

#### 2.1.1.10 Digital Controller BACnet Internetwork

Provide a BACnet internetwork with control products, communication media, connectors, repeaters, hubs, and routers. Provide intermediate gateways, only when requested by the Government and shown on the contract drawings, to connect existing non-BACnet devices to the BACnet internetwork. Controller and operator interface communication shall conform to [ASHRAE 135](#), BACnet. [Use the building's existing Ethernet backbone for network segments marked "existing" on project drawings. Coordinate connections to existing Ethernet backbones with the BAS Owner and LAN administrator.] If a controller becomes non-responsive, the remaining controllers shall continue operating and not be affected by the failed controller.

#### 2.1.1.11 Communications Ports

- a. Direct-Connect Interface Ports: Provide at least one extra communication port at each local BACnet network for direct connecting a notebook computer or BACnet hand-held terminal so all network BACnet objects and properties may be viewed and edited by the operator.
- b. Telecommunications Interface Port: Provide one telecommunication port per building, permitting remote communication via point-to-point (PTP) protocol over telephone lines.

#### 2.1.1.12 Modems

Provide [v.92] [DSL] modems where required for communication between the BACnet Operator Workstation (B-OWS) and the DDC system.

#### 2.1.1.13 BACnet Gateways

\*\*\*\*\*

**NOTE: Gateways require a good understanding of when and where to use them. Use Caution when trying to connect to non-BACnet DDC and OEM equipment. It may be more practical to select new equipment that is already "BACnet ready". Research gateway manufacturers for price, options, and performance before including in the design.**



When using gateways, they must be requested and approved by the Government and specifically shown on BACnet communication schematic architecture drawings.

For each gateway, the design needs to include an interoperability schedule showing each point or event on the legacy side that the BACnet "client" will read, and each parameter that the BACnet network will write to. Ideally, one should do this in terms of BACnet services, or BACnet Interoperability Building Blocks (BIBBs) defined in ASHRAE 135 Annex K.

\*\*\*\*\*  
Provide BACnet communication ports, whenever available as a plant equipment OEM standard option, for DDC integration via a single communication cable. Typical BACnet controlled plant equipment includes, but is not limited to, boilers, chillers, and variable frequency motor drives.

Provide gateways to connect BACnet to legacy systems, existing non-BACnet devices, and existing non-BACnet DDC controlled plant equipment, only when specifically requested and approved by the Government, and shown on the Government approved BACnet Communication Architecture Schematic. Provide with each gateway an interoperability schedule [Use gateway interoperability schedules shown on design drawings or other project documents], showing each point or event on the legacy side that the BACnet "client" will read, and each parameter that the BACnet network will write to. Describe this interoperability in terms of BACnet services, or Interoperability Building Blocks (BIBBs), defined in ASHRAE 135 Annex K. Provide two-year minimum warranty for each gateway, including parts and labor.

The following minimum capabilities are required:

- a. Gateways shall be able to read and view all readable object properties listed in the interoperability schedule on the non-BACnet network to the BACnet network and vice versa where applicable.
- b. Gateways shall be able to write to all writeable object properties listed in the interoperability schedule on the non-BACnet network from the BACnet network and vice versa where applicable.
- c. Gateways shall provide single-pass (only one protocol to BACnet without intermediary protocols) translation from the non-BACnet protocol to BACnet and vice versa.
- d. Gateways shall meet the requirements of Data Sharing Read Property (DS-RP-B), Data Sharing Write Property (DS-WP-B), Device Management Dynamic Device Binding-B (DM-DDB-B), and Device Management Communication Control (DM-DCC-B) BIBBs, in accordance with **ASHRAE 135**.
- e. Gateways shall include all hardware, software, software licenses, and configuration tools for operator-to-gateway communications. Provide backup programming and parameters on CD media and the ability to modify, download, backup, and restore gateway configuration.

#### 2.1.1.14 Digital Controller Cabinet

\*\*\*\*\*

NOTE: Indicate control devices that must be in enclosures with more stringent requirements than NEMA 1 or NEMA 4.

\*\*\*\*\*

Provide each digital controller in a factory fabricated cabinet enclosure. Cabinets located indoors shall protect against dust and have a minimum NEMA 1 rating, except where indicated otherwise. Cabinets located outdoors or in damp environments shall protect against all outdoor conditions and have a minimum NEMA 4 rating. Outdoor control panels and controllers must be able to withstand extreme ambient conditions, without malfunction or failure, whether or not the controlled equipment is running. If necessary, provide a thermostatically controlled panel heater in freezing locations, and an internal ventilating fan in locations exposed to direct sunlight. Cabinets shall have a hinged lockable door and an offset removable metal back plate, except controllers integral with terminal units, like those mounted on VAV boxes. Provide like-keyed locks for all hinged panels provided and a set of two keys at each panel, with one key inserted in the lock.

#### 2.1.1.15 Main Power Switch and Receptacle

Provide each control cabinet with a main external power on/off switch located inside the cabinet. Also provide each cabinet with a separate 120 VAC duplex receptacle.

#### 2.1.2 DDC Software

\*\*\*\*\*

NOTE: Provide a complete, clear, and concise written sequence of operation for the HVAC equipment. Include all conventional control operations, time event operations, energy management functions (night setback, reset schedules, optimum start), push button overrides, demand limiting, safeties, and emergency conditions. Put the sequence of operation on the design drawings, not in the specifications.

\*\*\*\*\*

##### 2.1.2.1 Programming

\*\*\*\*\*

NOTE: Graphic-based programming is available from many vendors and is preferred to line-by-line programming because it is easier to document, learn and troubleshoot.

Many manufacturers use menu-based programming that is also easy to learn, but may not document the sequences visually, and is arguably not as flexible as graphic programming..

Text-based or line-by-line programming is flexible, but difficult to standardize and troubleshoot. It requires more time to learn, and is sometimes difficult to follow what others have written.

\*\*\*\*\*  
Provide programming to execute the sequence of operation indicated.  
Provide all programming and tools to configure and program all  
controllers. Provide programming routines in simple, easy-to-follow logic  
with detailed text comments describing what the logic does and how it  
corresponds to the project's written sequence of operation.

- a. Graphic-based programming shall use a library of function blocks made from pre-programmed code designed for BAS control. Function blocks shall be assembled with interconnecting lines, depicting the control sequence in a flowchart. If providing a computer with device programming tools as part of the project, graphic programs shall be viewable in real time showing present values and logical results from each function block.
- b. Menu-based programming shall be done by entering parameters, definitions, conditions, requirements, and constraints.
- c. For line-by-line and text-based programming, declare variable types (local, global, real, integer, etc.) at the beginning of the program. Use descriptive comments frequently to describe the programming.
- d. If providing a computer with device programming tools as part of the project, provide a means for detecting program errors and testing software strategies with a simulation tool. Simulation may be inherent within the programming software suite, or provided by physical controllers mounted in a NEMA 1 test enclosure. The test enclosure shall contain one dedicated controller of each type provided under this contract, complete with power supply and relevant accessories.

#### 2.1.2.2 Parameter Modification

All writeable object properties, and all other programming parameters needed to comply with the project specification shall be adjustable for devices at any network level, including those accessible with web-browser communication, and regardless of programming methods used to create the applications.

#### 2.1.2.3 Short Cycling Prevention

Provide setpoint differentials and minimum on/off times to prevent equipment short cycling.

#### 2.1.2.4 Equipment Status Delay

Provide an adjustable delay from when equipment is commanded on or off and when the control program looks to the status input for confirmation.

#### 2.1.2.5 Run Time Accumulation

Use the Elapsed Time Property to provide re-settable run time accumulation for each Binary Output Object connected to mechanical loads greater than 1 HP, electrical loads greater than 10 KW, or wherever else specified.

#### 2.1.2.6 Timed Local Override

Provide an adjustable override time for each push of a timed local override

button.

#### 2.1.2.7 Time Synchronization

Provide time synchronization, including adjustments for leap years, daylight saving time, and operator time adjustments.

#### 2.1.2.8 Scheduling

Provide operating schedules as indicated, with equipment assigned to groups. Changing the schedule of a group shall change the operating schedule of all equipment in the group. Groups shall be capable of operator creation, modification, and deletion. Provide capability to view and modify schedules in a seven-day week format. Provide capability to enter holiday and override schedules one full year at a time.

#### 2.1.2.9 Object Property Override

Allow writeable object property values to accept overrides to any valid value. Where specified or required for the sequence of control, the Out\_Of\_Service property of Objects shall be modifiable using BACnet's write property service. When documented, exceptions to these requirement are allowed for life, machine, and process safeties.

#### 2.1.2.10 Alarms and Events

Alarms and events shall be capable of having programmed time delays and high-low limits. When a computer workstation or web server is connected to the BACnet internetwork, alarms/events shall report to the computer, printer, [alphanumeric pager,][ e-mail,][ cell phone,] as defined by an authorized operator. Otherwise alarms/events shall be stored within a device on the BACnet network until connected to a user interface device and retrieved. Provide alarms/events in agreement with the point schedule, sequence of operation, and the BAS Owner. At a minimum, provide programming to initiate alarms/events any time a piece of equipment fails to operate, a control point is outside normal range or condition shown on schedules, communication to a device is lost, a device has failed, or a controller has lost its memory.

#### 2.1.2.11 Trending

Provide BACnet trend services capable of trending all object present values set points, and other parameters indicated for trending on project schedules. Trends may be associated into groups, and a trend report may be set up for each group. Trends are stored within a device on the BACnet network, with operator selectable trend intervals from 10 seconds up to 60 minutes. The minimum number of consecutive trend values stored at one time shall be 100 per variable. When trend memory is full, the most recent data shall overwrite the oldest data.

The operator workstation shall upload trends automatically upon reaching 3/4 of the device buffer limit (via Notification\_Threshold property), by operator request, or by time schedule for archiving. Archived and real-time trend data shall be available for viewing numerically and graphically for at the workstation and connected notebook computers.

#### 2.1.2.12 Device Diagnostics

Each controller shall have diagnostic LEDs for power, communication, and

device fault condition. The DDC system shall recognize and report a non-responsive controller.

#### 2.1.2.13 Power Loss

Upon restoration of power, the DDC system shall perform an orderly restart and restoration of control.

#### 2.1.3 BACnet Operator Workstation

\*\*\*\*\*  
**NOTE: Delete this paragraph and subparagraphs below  
when a new operator workstation is not required.**  
\*\*\*\*\*

The workstation shall be capable of accessing all DDC system devices and communicate using the BACnet protocol. The workstation shall be capable of displaying, modifying, creating, archiving, and deleting (as applicable): all points, objects, object properties, programming, alarms, trends, messages, schedules, and reports.

##### 2.1.3.1 BACnet Operator Workstation Hardware

\*\*\*\*\*  
**NOTE: Update computer criteria as technology  
dictates.**  
\*\*\*\*\*

Configure according to system manufacturer's specifications and conforming to BACnet Operator Workstation (B-OWS) device standards found in [ASHRAE 135](#), Annex L. Install to permit complete monitoring and troubleshooting of the DDC system.

At a minimum the workstation hardware shall include:  
a desktop personal computer with Microsoft Windows XP or VISTA Professional operating system or equal, processor and RAM exceeding capability and speed required by operating system and application software, hard drive capacity exceeding software and yearly archive requirements, 16X internal DVD+/-R/RW/CD-RW drive with archive creator software, [external 200 GB USB 2.0 hard drive and cable,] 4 USB 2.0 ports, 10/100 network interface card, [MS/TP card,] 19-inch LCD monitor, internal V.92 modem, sound card with speakers, 101 character keyboard, optical mouse, USB Hub with four USB 2.0 ports and connecting cable, [ink jet] [laser] printer with USB port and cable, [3 matching toner cartridges] [3 matching color and black ink cartridges], 120-volt 800 VA uninterruptible power supply with automatic voltage regulation and 4 minimum battery back-up outlets and 2 surge protected outlets, [[Microsoft Office bundled software,] [Adobe Acrobat Writer,] [and Symantec Ghost disk imaging software or equal]]. Provide all original licenses, installation media, documentation, and recovery CDs capable of restoring the original configuration. Provide a manufacturer's 3-year next business day on-site warranty with the Government listed as the warranty owner.

##### 2.1.3.2 Password Protection

Provide at least five levels of password protection for operator interfaces. The lowest level only allow viewing graphics. The second level allows viewing graphics and changing space temperature setpoints. The third level allows the previous level's capability, plus changing operating schedules. The fourth level allows access to all functions except passwords. The highest level provides all administrator rights and

allows full access to all programming, including setting new passwords and access levels. Provide the BAS Owner with the highest level password access. Provide automatic log out if no keyboard or mouse activity is detected after a user-defined time delay.

#### 2.1.3.3 BACnet Operator Workstation DDC Software

Provide the workstation software with the manufacturer's installation CDs and licenses. Configure the software according to the DDC system manufacturer's specifications and in agreement with BACnet Operator Workstation (B-OWS) device standards found in [ASHRAE 135](#), Annex L.

The workstation software shall permit complete monitoring, modification, and troubleshooting interface with the DDC system. The operator interface with the software shall be menu-driven with appropriate displays and menu commands to manipulate the DDC system's objects, point data, operating schedules, control routines, system configuration, trends, alarms, messages, graphics, and reports. Trends shall be capable of graphic display in real time, with variables plotted as functions of time. Each alarmed point shall be capable of displaying its alarm history, showing when it went into alarm, if and when it was acknowledged, and when it went out of alarm. The modification of DDC system parameters and object properties shall be accomplished with "fill in the blank" and/or "point and drag" methods. Modifications shall download to the appropriate controllers at the operator's request.

#### 2.1.3.4 Graphics Software

Provide web-based system graphics viewable on browsers compatible with MS Internet Explorer 6.X or greater using an industry-standard file format such as HTML, BMP, JPEG, or GIF.

Graphic displays shall have full-screen resolution when viewed on the workstation and notebook computers. Dynamic data on graphics pages shall refresh within 10 seconds using an Internet connection, or 30 seconds using a dial-up modem connection. Graphics viewing shall not require additional "plug-in" software like Java, Shockwave and Flash applications unless the software is readily available for free over the Internet, and certified for use with Navy Marine Corps Internet (NMCI) personal computers.

The graphics shall show the present value and object name for each of the project's I/O points on at least one graphic page. Arrange point values and names on the graphic displays in their appropriate physical locations with respect to the floor plan or equipment graphic displayed. Graphics shall allow the operator to monitor current status, view zone and equipment summaries, use point-and-click navigation between graphic pages, and edit setpoints and parameters directly from the screens. Items in alarm shall be displayed using a different color or other obvious visual indicator. Provide graphics with the following:

- a. Graphic Types: Provide at least one graphic display for each piece of HVAC equipment, building floor, and controlled zone. Indicate dynamic point values, operating statuses, alarm conditions, and control setpoints on each display. Provide summary pages where appropriate.
  - (1) Building Elevation: For buildings more than one story, provide an elevation view of the building with links to each of the building's floor plans. Simulate the building's architecture

and include the building number and floor numbers. If possible, use an actual photograph of the building.

(2) Building Floor Plans: Provide a floor plan graphic for each of the building's floors [and roof] with dynamic display of space temperature and other important data. If used, indicate and provide links to sub-plan areas. If possible, use the project's electronic drawing files for the graphic backgrounds. Provide clear names for important areas, such as "Main Conference Room." Include room names and numbers where applicable. Include features such as stairwells, elevators, and main entrances. Where applicable, include the mechanical room, HVAC equipment, and control component locations, with corresponding links to the equipment graphics.

(3) Sub-plan Areas: Where a building's floor plan is too large to adequately display on the screen, sub-divide the plan into distinct areas, and provide a separate graphic display for each area. Provide same level of detail requested in building floor plan section above.

(4) HVAC Equipment: Provide a graphic display for each piece of HVAC equipment, such as a fan coil unit, VAV terminal, or air handling unit. Equipment shall be represented by a two or three-dimensional drawing. Where multiple pieces of equipment combine to form a system, such as a central chiller plant or central heating plant, provide one graphic to depict the entire plant. Indicate the equipment, piping, ductwork, dampers, and control valves in the installed location. Include labels for equipment, piping, ductwork, dampers, and control valves. Show the direction of air and water flow. Include dynamic display of applicable object data with clear names in appropriate locations.

(5) Sequence of Operation: Provide a graphic screen displaying the written out full sequence of operation for each piece of HVAC equipment. Provide a link to the sequence of operation displays on their respective equipment graphics.[ Include dynamic real-time data within the text for setpoints and variables.]

- b. Graphic Title: Provide a prominent, descriptive title on each graphic page.
- c. Dynamic Update: When the workstation is on-line, all graphic I/O object values shall update with change-of-value services, or by operator selected discrete intervals.
- d. Graphic Linking: Provide forward and backward linking between floor plans, sub-plans, and equipment.
- e. Graphic Editing: Provide installed software to create, modify, and delete the DDC graphics. Include the ability to store graphic symbols in a symbol directory and import these symbols into the graphics.
- f. Dynamic Point Editing: Provide full editing capability for deleting, adding, and modifying dynamic points on the graphics.

#### 2.1.1.4 Notebook Computer

Provide a notebook computer, complete with the project's installed DDC software, applications database, and graphics to fully troubleshoot and program the project's devices. Notebook computers for web-based systems do not require this installed software if they have the ability to connect locally in real time, view all graphics, and fully troubleshoot, modify, and program all project devices. Provide the notebook computer with ballistic nylon carrying case with shoulder strap [on wheels with a telescoping handle ]with all necessary cables and interface hardware needed for setup and communication with the controllers and control system components.

At a minimum the notebook computer shall include: a Microsoft XP Professional operating system, processor with capability and speed required by application software, 40 giga-byte hard drive, 512 mega-byte RAM, 2 USB 2.0 ports, 10/100 network interface card, [ARCnet card,] [MS/TP card,] internal V.92 modem, 15-inch display, keyboard, 3-hour battery with charger, 52X internal CD-RW drive with CD creator software, [and Microsoft Office bundled software]. Provide all original licenses, installation media, documentation, and recovery CDs capable of restoring the original configuration. Provide the manufacturer's 3-year next business day on-site warranty with the Government listed as the warranty owner.

\*\*\*\*\*

NOTE: The BACnet Protocol Analyzer is typically software for connecting a computer to any BACnet network and sweeping it for basic system information. It is very useful for integration projects with poorly documented systems, or where different BACnet manufacturers reside on the same network.

It takes a moderate level of skill and knowledge to use and understand a Protocol Analyzer. Delete the requirement below if local users already have it, or if they are not interested in using it.

\*\*\*\*\*

#### 2.1.1.5 BACnet Protocol Analyzer

Provide a BACnet protocol analyzer and required cables and fittings for connection to the BACnet network. The analyzer shall include the following minimum capabilities:

- a. Capture and store to a file data traffic on all network levels.
- b. Measure bandwidth usage.
- c. Filtering options with ability to ignore select traffic.

#### 2.2 SENSORS AND INPUT HARDWARE

Coordinate sensor types with the BAS Owner to keep them consistent with existing installations.

##### 2.2.1 Field-Installed Temperature Sensors

Where feasible, provide the same sensor type throughout the project. Avoid



using transmitters unless absolutely necessary.

#### 2.2.1.1 Thermistors

Precision thermistors may be used in applications below 200 degrees F. Sensor accuracy over the application range shall be 0.36 degree F or less between 32 to 150 degrees F. Stability error of the thermistor over five years shall not exceed 0.25 degree F cumulative. A/D conversion resolution error shall be kept to 0.1 degree F. Total error for a thermistor circuit shall not exceed 0.5 degree F.

#### 2.2.1.2 Resistance Temperature Detectors (RTDs)

Provide RTD sensors with platinum elements compatible with the digital controllers. Encapsulate sensors in epoxy, series 300 stainless steel, anodized aluminum, or copper. Temperature sensor accuracy shall be 0.1 percent (1 ohm) of expected ohms (1000 ohms) at 32 degrees F. Temperature sensor stability error over five years shall not exceed 0.25 degree F cumulative. Direct connection of RTDs to digital controllers without transmitters is preferred. When RTDs are connected directly, lead resistance error shall be less than 0.25 degrees F. The total error for a RTD circuit shall not exceed 0.5 degree F.

#### 2.2.1.3 Temperature Sensor Details

\*\*\*\*\*  
**NOTE: Where feasible, include a supply air  
temperature sensor for all air handling, fan coil,  
and VAV terminal units for troubleshooting and  
performance monitoring.**  
\*\*\*\*\*

- a. Room Type: Provide the sensing element components within a decorative protective cover suitable for surrounding decor.  
[Provide room temperature sensors with timed override button, setpoint adjustment lever, digital temperature display.]  
[Provide a communication port or 802.11x wireless support for a portable operator interface like a notebook computer or PDA.]
- b. Duct Probe Type: Ensure the probe is long enough to properly sense the air stream temperature.
- c. Duct Averaging Type: Continuous averaging sensors shall be one foot in length for each 4 square feet of duct cross-sectional area, and a minimum length of 6 ft.
- d. Pipe Immersion Type: Provide minimum three-inch immersion. Provide each sensor with a corresponding pipe-mounted sensor well, unless indicated otherwise. Sensor wells shall be stainless steel when used in steel piping, and brass when used in copper piping. Provide the sensor well with a heat-sensitive transfer agent between the sensor and the well interior.
- e. Outside Air Type: Provide the sensing element on the building's north side with a protective weather shade that positions the sensor approximately 3 inches off the wall surface, does not inhibit free air flow across the sensing element, and protects the sensor from snow, ice, and rain.

### 2.2.2 Transmitters

Provide transmitters with 4 to 20 mA or 0 to 10 VDC linear output scaled to the sensed input. Transmitters shall be matched to the respective sensor, factory calibrated, and sealed. Size transmitters for an output near 50 percent of its full-scale range at normal operating conditions. The total transmitter error shall not exceed 0.1 percent at any point across the measured span. Supply voltage shall be 12 to 24 volts AC or DC. Transmitters shall have non-interactive offset and span adjustments. For temperature sensing, transmitter drift shall not exceed 0.03 degrees F a year.

#### 2.2.2.1 Relative Humidity Transmitters

\*\*\*\*\*  
**NOTE: Even on projects without direct humidity control, include room RH sensors in important areas for monitoring at the workstation.**  
\*\*\*\*\*

Provide transmitters with an accuracy equal to plus or minus 3 [2] [5] percent from 0 to 90% scale, and less than one percent drift per year. Sensing elements shall be the polymer type.

#### 2.2.2.2 Pressure Transmitters

Provide transmitters integral with the pressure transducer.

#### 2.2.3 Current Transducers

Provide current transducers to monitor motor amperage, unless current switches are shown on design drawings or point tables.

#### 2.2.4 Pneumatic to Electric Transducers

Pneumatic to electronic transducers shall convert a 0 to 20 psig signal to a proportional 4 to 20 mA or 0 to 10 VDC signal (operator scaleable). Supply voltage shall be 24 VDC. Accuracy and linearity shall be 1.0 percent or better.

#### 2.2.5 Air Quality Sensors

\*\*\*\*\*  
**NOTE: Choose between CO2 sensors and air quality sensors, or use both. CO2 sensors provide information to ensure adequate ventilation. Air quality sensors are useful to monitor areas vulnerable to organic contaminants like car exhaust and industrial solvents.**  
\*\*\*\*\*  
Provide power supply for each sensor.

##### 2.2.5.1 CO2 Sensors

Provide photo-acoustic type CO2 sensors with integral transducers and linear output. The devices shall read CO2 concentrations between 0 and 2000 ppm with full scale accuracy of at least plus or minus 100 ppm.

#### 2.2.5.2 Air Quality Sensors

Provide full spectrum air quality sensors using a hot wire element based on the Taguchi principle. The sensor shall monitor a wide range of gaseous volatile organic components common in indoor air contaminants like paint fumes, solvents, cigarette smoke, and vehicle exhaust. The sensor shall automatically compensate for temperature and humidity, have span and calibration potentiometers, operate on 24 VDC power with output of 0-10 VDC, and have a service rating of 32 to 140 degrees F and 5 to 95 percent relative humidity.

#### 2.2.6 Input Switches

##### 2.2.6.1 Timed Local Overrides

Provide buttons or switches to override the DDC occupancy schedule programming for each major building zone during unoccupied periods, and to return HVAC equipment to the occupied mode. This requirement is waived for zones clearly intended for 24 hour continuous operation.

#### 2.2.7 Freeze Protection Thermostats

Provide special purpose thermostats with flexible capillary elements 20 feet minimum length for coil face areas up to 40 square feet. Provide longer elements for larger coils at 1-foot of element for every 4 square feet of coil face area, or provide additional thermostats. Provide switch contacts rated for the respective motor starter's control circuit voltage. Include auxiliary contacts for the switch's status condition. A freezing condition at any 18-inch increment along the sensing element's length shall activate the switch. The thermostat shall be equipped with a manual push-button reset switch so that when tripped, the thermostat requires manual resetting before the HVAC equipment can restart.

#### 2.2.8 Air Flow Measurement Stations

Air flow measurement stations shall have an array of velocity sensing elements and straightening vanes inside a flanged sheet metal casing. The velocity sensing elements shall be the RTD or thermistor type, traversing the ducted air in at least two directions. The air flow pressure drop across the station shall not exceed 0.08 inch water gage at a velocity of 2,000 fpm. The station shall be suitable for air flows up to 5,000 fpm, and a temperature range of 40 to 120 degrees F. The station's measurement accuracy over the range of 125 to 2,500 fpm shall be plus or minus 3 percent of the measured velocity. Station transmitters shall provide a linear, temperature-compensated 4 to 20 mA or 0 to 10 VDC output. The output shall be capable of being accurately converted to a corresponding air flow rate in cubic feet per minute. Transmitters shall be a 2-wire, loop powered device. The output error of the transmitter shall not exceed 0.5 percent of the measurement.

#### 2.2.9 Energy Metering

\*\*\*\*\*  
**NOTE: Metering requirements are in the NAVFAC  
Maintenance Manual, MO-221 Utilities Metering. Also  
determine local needs of the BAS Owner and show  
meters on the drawings.**  
\*\*\*\*\*

### 2.2.9.1 Electric Meters

\*\*\*\*\*  
**NOTE: Use the first paragraph when electric meters are covered under another section, and delete the second paragraph. Otherwise, delete the first paragraph and use the second.**  
\*\*\*\*\*

[Provide kilowatt-hour (kWh) meter(s) shown as specified in Section [\_\_\_\_\_, "\_\_\_\_\_" ]]

[Provide kilowatt-hour (kWh) meter(s) shown in accordance with **NFLPA C12.10**, suitable for the intended voltage, phases, and wye/delta configuration, with three current transformers and an output signal compatible with the DDC system. The meter shall have a box-mounted socket and an automatic circuit-closing bypass. Provide the meter with at least four pointer-type kWh registers, provisions for pulse initiation, and universal Class 2 indicating maximum kW demand register, sweep pointer indicating type, and a [15] [30] [60] minute interval. The meter accuracy shall be within plus or minus one percent of the actual kWh. Provide the correct multiplier on the meter face. Provide the current transformers in accordance with **IEEE C57.13**, with 600-volt insulation, and rated for metering with voltage, IL, momentary, and burden ratings coordinated with the ratings of corresponding meters. Provide butyl-molded donut or window type transformers mounted on a bracket to allow secondary cables to connect to the transformer bushings. Provide wiring identification of the current transformer secondary feeders to permit field measurements to be taken with hook-on ammeters.]

\*\*\*\*\*  
**NOTE: Locate steam meters according to ASME, Fluid Meters; Theory and Applications.**  
\*\*\*\*\*

### 2.2.9.2 Steam Meters

Steam meters shall be the vortex type, with pressure compensation, a minimum turndown ratio of 10 to 1, and an output signal compatible with the DDC system.

## 2.3 OUTPUT HARDWARE

### 2.3.1 Control Dampers

\*\*\*\*\*  
**NOTE: Show all control dampers on the control drawings. Indicate the blade configuration (parallel or opposed-blade), the actuator normal position, and whether it's two-position or modulating. Where desired, provide a switch on the linkage to indicate the damper status.**  
\*\*\*\*\*

Control dampers shall conform to **SMACNA HVAC Duct Const Stds**.

- a. For field-installed dampers, a single damper section shall have blades no longer than **1220 mm 48 inches** and no higher than **1830 mm 72 inches**. The maximum damper blade width shall be **203 mm 8 inches**. Larger sized dampers shall be built using a combination of sections.
- b. Dampers shall be [stainless ] [galvanized ] steel construction, unless indicated otherwise. Frames shall be at least **2 inches**

wide. Flat blades shall have edges folded for rigidity. Blades shall be provided with compressible gasket seals along the full length of the blades to prevent air leakage when closed. The damper frames shall be provided with jamb seals to minimize air leakage. Seals shall be suitable for an operating temperature range of minus 40 degrees C to 93 degrees C 40 degrees F to 200 degrees F. The leakage rate of each damper when full-closed shall be no more than 20 cfm per square foot of damper face area at 996 Pa 4 inches water gage static pressure. Dampers shall be rated for not less than 10 m/s 2000 fpm air velocity. Damper axles shall be 13 mm minimum 0.5 inches diameter plated steel rods supported in the damper frame by stainless steel or bronze bearings. Blades mounted vertically shall be supported by thrust bearings. The pressure drop through each damper when full-open shall not exceed 10 Pa gage at 5 m/s 0.04 inches water gage at 1000 fpm face velocity. Damper leakage rates and pressure drops shall be tested in accordance with AMCA 500-D.

- c. The damper operating linkages external to dampers (such as crank arms, connecting rods, and other hardware that transmits motion from the damper actuators to the dampers) shall be adjustable, and capable of withstanding a load equal to twice the maximum required damper-operating force. Linkages shall be brass, bronze, galvanized steel, or stainless steel.

## 2.3.2 Control Valves

### 2.3.2.1 Valve Assembly

\*\*\*\*\*

NOTE: Select valve Cv so pressure drops are within the constraints of the available pressures, pipe velocities, economy of design, and noise criteria. Do not oversize control valves. Size steam valves using the critical pressure drop (0.45 of absolute pressure). In the absence of other sizing criteria, size modulating hot and chilled water coil control valves for a pressure drop of 21 kPa 2 psi to 4 psi. List the calculated minimum and maximum Cvs in the drawing's valve schedule.

\*\*\*\*\*

Valve bodies shall be designed for 125 psig minimum working pressure or 150 percent of the operating pressure, whichever is greater. Valve stems shall be Type 316 stainless steel. Valve leakage ratings shall be 0.01 percent of rated Cv value. Class 125 copper alloy valve bodies and Class 150 steel or stainless steel valves shall meet the requirements of ASME B16.5. Cast iron valve components shall meet the requirements of ASTM A 126 Class B or C.

### 2.3.2.2 Butterfly Valves

Butterfly valves shall be the threaded lug type suitable for dead-end service and for modulation to the fully-closed position, with stainless steel shafts supported by bearings, non-corrosive discs geometrically interlocked with or bolted to the shaft (no pins), and EPDM seats suitable for temperatures from minus 29 degrees C to plus 121 degrees C minus 20 degrees F to plus 250 degrees F. Valves shall have a means of manual operation independent of the actuator.

#### 2.3.2.3 Two-Way Valves

Two-way modulating valves shall have an equal percentage characteristic.

#### 2.3.2.4 Three-Way Valves

Three-way valves shall have an equal percentage characteristic.

#### 2.3.2.5 Valves for Chilled Water, Condenser Water, and Glycol Fluid Service

- a. Bodies for valves 40 mm 1 1/2 inches and smaller shall be brass or bronze, with threaded or union ends. Bodies for valves from 50 to 80 mm 2 inches to 3 inches inclusive shall be of brass, bronze, or iron. Bodies for 50 mm 2 inch valves shall have threaded connections. Bodies for valves from 65 to 80 mm 2 1/2 to 3 inches shall have flanged connections.
- b. Internal valve trim shall be brass or bronze, except that valve stems shall be stainless steel.
- c. Unless indicated otherwise, provide modulating valves sized for 2 psi minimum and 4 psi maximum differential across the valve at the design flow rate.
- d. Valves 100 mm 4 inches and larger shall be butterfly valves, unless indicated otherwise.

#### 2.3.2.6 Valves for Hot Water Service

Valves for hot water service below 121 degrees C 250 Degrees F:

- a. Bodies for valves 40 mm 1 1/2 inches and smaller shall be brass or bronze, with threaded or union ends. Bodies for valves from 50 to 80 mm 2 inches to 3 inches inclusive shall be of brass, bronze, or iron. Bodies for 50 mm 2 inch valves shall have threaded connections. Bodies for valves from 65 to 80 mm 2 1/2 to 3 inches shall have flanged connections.
- b. Internal trim (including seats, seat rings, modulation plugs, valve stems, and springs) of valves controlling water above 99 degrees C 210 degrees F shall be Type 316 stainless steel.
- c. Internal trim for valves controlling water 99 degrees C 210 degrees F or less shall be brass or bronze. Valve stems shall be Type 316 stainless steel.
- d. Non-metallic parts of hot water control valves shall be suitable for a minimum continuous operating temperature of 121 degrees C or 28 degrees C 250 degrees F or 50 degrees F above the system design temperature, whichever is higher.
- e. Unless indicated otherwise, provide modulating valves sized for 2 psi minimum and 4 psi maximum differential across the valve at the design flow rate.
- f. Valves 100 mm 4 inches and larger shall be butterfly valves, unless indicated otherwise.

#### 2.3.2.7 Valves for High Temperature Hot Water Service

Valves for hot water service 121 degrees Cabove 250 Degrees F:

- a. Valve bodies shall conform to ASME B16.34 Class 300. Valve and actuator combination shall be normally closed. Bodies shall be carbon steel, globe type with welded ends on valves 25 mm 1 inch and larger. Valves smaller than 25 mm 1 inch shall have socket-weld ends. Packing shall be virgin polytetrafluoroethylene (PTFE).
- b. Internal valve trim shall be Type 316 stainless steel.
- c. Unless indicated otherwise, provide modulating valves sized for 2 psi minimum and 4 psi maximum differential across the valve at the design flow rate.

#### 2.3.2.8 Valves for Steam Service

The entire body for valves 40 mm 1 1/2 inches and smaller shall be brass or bronze, with threaded or union ends. Bodies for valves from 50 to 80 mm 2 to 3 inches inclusive shall be of brass, bronze, or carbon steel. Bodies for valves 100 mm 4 inches and larger shall be carbon steel. Bodies for 50 mm 2 inch valves shall have threaded connections. Bodies for valves 65 mm 2 1/2 inches and larger shall have flanged connections. Steam valves shall be sized for [103 kPa (gage)] [15 psig] [\_\_\_\_\_] inlet steam pressure with a maximum [90 kPa] [13 psi] [\_\_\_\_\_] differential through the valve at rated flow, except where indicated otherwise. Internal valve trim shall be Type 316 stainless steel.

#### 2.3.3 Actuators

Provide direct-drive electric actuators for all control applications, except where indicated otherwise.

\*\*\*\*\*

NOTE: Show on drawings the normal position of each actuator without power or control signal. Select normal position considering power loss, freezing, moisture damage, and smoke or fire transmission. Indicate power return actuators where necessary for actuator timing and process requirements. Indicate spring return for actuators where normal position, but not timing, is important. Spring return closed is often desirable for steam valves and outside air

Whenever possible provide electric actuators for reduced maintenance, quality control, and DDC integration. However, pneumatic actuators may be preferable in unusual circumstances like explosion-proof areas. Existing pneumatic actuators may also have to remain in retrofits where costs prevent actuator replacement.

\*\*\*\*\*

##### 2.3.3.1 Electric Actuators

Each actuator shall deliver the torque required for continuous uniform motion and shall have internal end switches to limit the travel, or be capable of withstanding continuous stalling without damage. Actuators

shall function properly within 85 to 110 percent of rated line voltage. Provide actuators with hardened steel running shafts and gears of steel or copper alloy. Fiber or reinforced nylon gears may be used for torques less than 16 inch-pounds. Provide two-position actuators of single direction, spring return, or reversing type. Provide modulating actuators capable of stopping at any point in the cycle, and starting in either direction from any point. Actuators shall be equipped with a switch for reversing direction, and a button to disengage the clutch to allow manual adjustments. Provide the actuator with a hand crank for manual adjustments, as applicable. Thermal type actuators may only be used on terminal fan coil units, terminal VAV units, convectors, and unit heaters. Spring return actuators shall be provided on all control dampers and all control valves except terminal fan coil units, terminal VAV units, convectors, and unit heaters; unless indicated otherwise. Each actuator shall have distinct markings indicating the full-open and full-closed position, and the points in-between.

#### 2.3.3.2 Pneumatic Actuators

\*\*\*\*\*  
**NOTE: Delete this paragraph and the following  
subparagraphs for pneumatic devices if not used.**  
\*\*\*\*\*

Provide piston or diaphragm type actuators

#### 2.3.4 Output Signal Conversion

##### 2.3.4.1 Electronic-to-Pneumatic Transducers

Electronic to pneumatic transducers shall convert a 4 to 20 mA or 0 to 10 VDC digital controller output signal to a proportional 0 to 20 psig pressure signal (operator scaleable). Accuracy and linearity shall be 1.0 percent or better. [ Transducers shall have feedback circuit that converts the pneumatic signal to a proportional 4 to 20 mA or 0 to 10 VDC signal.]

#### 2.3.5 Output Switches

##### 2.3.5.1 Control Relays

Field installed and DDC panel relays shall be double pole, double throw, UL listed, with contacts rated for the intended application, indicator light, and dust proof enclosure. The indicator light shall be lit when the coil is energized and off when coil is not energized. Relays shall be the socket type, plug into a fixed base, and replaceable without tools or removing wiring. Encapsulated "PAM" type relays may be used for terminal control applications.

#### 2.4 ELECTRICAL POWER AND DISTRIBUTION

\*\*\*\*\*  
**NOTE: In most cases, use Section 26 20 00 INTERIOR  
DISTRIBUTION SYSTEM, for specifying electrical power  
and wiring. Delete redundant or ambiguous  
paragraphs from this specification section upon  
coordination with Section 26 20 00 .**  
\*\*\*\*\*



#### 2.4.1 Transformers

Transformers shall conform to [UL 506](#). For control power other than terminal level equipment, provide a fuse or circuit breaker on the secondary side of each transformer.

#### 2.4.2 Surge and Transient Protection

Provide each digital controller with surge and transient power protection. Surge and transient protection shall consist of the following devices, installed externally to the controllers.

##### 2.4.2.1 Power Line Surge Protection

Provide surge suppressors on the incoming power at each controller or grouped terminal controllers. Surge suppressors shall be rated in accordance with [UL 1449](#), have a fault indicating light, and conform to the following:

- a. The device shall be a transient voltage surge suppressor, hard-wire type individual equipment protector for 120 VAC/1 phase/2 wire plus ground.
- b. The device shall react within 5 nanoseconds and automatically reset.
- c. The voltage protection threshold, line to neutral, shall be no more than 211 volts.
- d. The device shall have an independent secondary stage equal to or greater than the primary stage joule rating.
- e. The primary suppression system components shall be pure silicon avalanche diodes.
- f. The secondary suppression system components shall be silicon avalanche diodes or metal oxide varistors.
- g. The device shall have an indication light to indicate the protection components are functioning.
- h. All system functions of the transient suppression system shall be individually fused and not short circuit the AC power line at any time.
- i. The device shall have an EMI/RFI noise filter with a minimum attenuation of 13 dB at 10 kHz to 300 MHz.
- j. The device shall comply with [IEEE C62.41.1](#) and [IEEE C62.41.2](#), Class "B" requirements and be tested according to [IEEE C62.45](#).
- k. The device shall be capable of operating between -20 degrees F and +122 degrees F.

##### 2.4.2.2 Telephone and Communication Line Surge Protection

Provide surge and transient protection for DDC controllers and DDC network related devices connected to phone and network communication lines, in accordance with the following:

- a. The device shall provide continuous, non-interrupting protection, and shall automatically reset after safely eliminating transient surges.
- b. The protection shall react within 5 nanoseconds using only solid-state silicon avalanche technology.
- c. The device shall be installed at the distance recommended by its manufacturer.

#### 2.4.2.3 Controller Input/Output Protection

Provide controller inputs and outputs with surge protection via optical isolation, metal oxide varistors (MOV), or silicon avalanche devices. Fuses are not permitted for surge protection.

#### 2.4.3 Wiring

Provide complete electrical wiring for the DDC System, including wiring to transformer primaries. Unless indicated otherwise, provide all normally visible or otherwise exposed wiring in conduit. Where conduit is required, control circuit wiring shall not run in the same conduit as power wiring over 100 volts. [Circuits operating at more than 100 volts shall be in accordance with Section 26 20 00, INTERIOR DISTRIBUTION SYSTEM.] Run all circuits over 100 volts in conduit, metallic tubing, covered metal raceways, or armored cable. Use plenum-rated cable for circuits under 100 volts in enclosed spaces. Examples of these spaces include HVAC plenums, within walls, above suspended ceilings, in attics, and within ductwork.

##### 2.4.3.1 Power Wiring

The following requirements are for field-installed wiring:

- a. Wiring for 24 V circuits shall be insulated copper 18 AWG minimum and rated for 300 VAC service.
- b. Wiring for 120 V circuits shall be insulated copper 14 AWG minimum and rated for 600 VAC service.

##### 2.4.3.2 Analog Signal Wiring

Field-installed analog signal wiring shall be 18 AWG single or multiple twisted pair. Each cable shall be 100 percent shielded and have a 20 AWG drain wire. Each wire shall have insulation rated for 300 VAC service. Cables shall have an overall aluminum-polyester or tinned-copper cable-shield tape.

#### 2.5 FIRE PROTECTION DEVICES

##### 2.5.1 Duct Smoke Detectors

Provide duct smoke detectors in HVAC ducts in accordance with NFPA 72 and NFPA 90A, except as indicated otherwise. Provide UL listed or FM approved detectors, designed specifically for duct installation.

\*\*\*\*\*

**NOTE: Choose one of the three paragraphs below. Use the following paragraph (and delete the other two)**

if the project includes Section 28 31 74.00 20  
INTERIOR FIRE DETECTION AND ALARM SYSTEM

\*\*\*\*\*

[Furnish detectors under Section 28 31 74.00 20 INTERIOR FIRE  
DETECTION AND ALARM SYSTEM and install under this section.  
Connect new detectors to the building fire alarm panel.]

\*\*\*\*\*

NOTE: Use the following paragraph (and delete the  
other two) if the building has an existing fire  
alarm system. For connection to the existing  
system, the designer must determine if the existing  
fire alarm control panel is compatible with smoke  
detectors and has spare zone capacity. When in  
doubt, leave the choice of a connection to the fire  
alarm panel or a separate control unit in the  
paragraph. For some antiquated alarm systems, it  
may be necessary to replace the control panel, then  
Section 13852N, "Interior Fire Alarm System" must be  
included in the project, and the previous paragraph  
would be used.

\*\*\*\*\*

[Provide [ionization] [or] [photoelectric] type detectors. Detectors  
shall detect both visible and invisible particles of combustion,  
and shall not be susceptible to undesired operation by changes to  
relative humidity. Provide each detector with an approved duct  
housing mounted exterior to the duct, and an integral perforated  
sampling tube extending across the width of the duct. The  
detector housing shall have indicator lamps that light when the  
detector is powered and when the detector is activated. Each  
detector shall have an integral test port [, test switch] [and]  
[or] [, remote keyed test device]. Connect new detectors to the  
building's [new] [existing] fire alarm control panel. Provide  
control and power modules required for the operation of the  
detectors [in their own new control unit] [or] [integral with the  
existing fire alarm panel]. A ground fault, break, or open  
condition in the electrical circuitry to any detector or its  
control or power unit shall cause activation of a trouble signal  
at the building fire alarm panel. Electrical supervision of  
wiring used exclusively for air-handling unit shutdown is not  
required, provided a break in the wiring would cause shutdown of  
the associated unit. Equipment and devices shall be compatible  
and operable in all respects with, and shall in no way impair the  
reliability or operational functions of, the [new] [existing] fire  
alarm system. [The building's existing fire alarm control panel  
was manufactured by [\_\_\_\_].] Provide descriptive zone labels at  
the [new] [existing] fire alarm panel indicating which new  
air-handling unit detectors they serve and their location. Label  
zones modified in order to accomplish the work.]

\*\*\*\*\*

NOTE: Use the paragraph below only with specific  
approval from NAVFAC Fire Protection Engineering.  
Approval is normally granted only if the building  
has no fire alarm system and none is required. When  
in doubt, contact the regional Fire Protection  
Engineer.

\*\*\*\*\*

[Provide [ionization] [or] [photoelectric] type detectors. Detectors shall detect both visible and invisible particles of combustion, and shall not be susceptible to undesired operation by changes to relative humidity. Provide each detector with an approved duct housing mounted exterior to the duct, and an integral perforated sampling tube extending across the width of the duct. The detector housing shall have indicator lamps that light when the detector is powered and when the detector is activated. Each detector shall have an integral test port [, test switch] [and] [or] [, remote keyed test device]. Provide a 115 VAC power supply unit integral with the detector's duct housing. Provide power to the detector from [the air-handling unit or air-handling unit controls] [the location indicated]. [Provide the detectors with a remote alarm indicator [and keyed test] device at [\_\_\_\_\_] [the location indicated].] [Provide each detector with a minimum 152 mm 6 inch diameter remote alarm bell located [as directed] [as indicated] in a normally occupied area.] Activation of a detector shall cause immediate shutdown of the associated air-handling unit [and the closing of its dampers] [and shall activate the remote alarm indicator] [and shall sound the remote alarm bell]. [Provide the remote alarm bell with a permanent label indicating its associated air-handling unit and air-handling unit location.]]

[Provide smoke control systems with a provision for manual operation by means of a key-operated switch to override the duct smoke detector shutdowns. Locate the override switch [adjacent to the building's fire alarm system control panel] [as indicated].]

## 2.6 INDICATORS

### 2.6.1 Thermometers

Provide bi-metal type thermometers at locations shown. Thermometers shall have either 9 inch long scales or 3.5 inch diameter dials, with insertion, immersion, or averaging elements. Provide matching thermowells for pipe-mounted installations. Select scale ranges suitable for the intended service, with the normal operating temperature near the scale's midpoint. The thermometer's accuracy shall be plus or minus 2 percent of the scale range.

### 2.6.2 Pressure Gauges for Piping Systems

Provide pipe-mounted pressure gauges at the locations shown. Gauges shall conform to ASME B40.100 and have a 4-inch diameter dial and shutoff cock. Provide gauges in steam piping with a pressure snubber pigtail fitting. Select scale ranges suitable for the intended service, with the normal operating pressure near the scale's midpoint. The gauge's accuracy shall be plus or minus 2 percent of the scale range.

### 2.6.3 Pressure Gauges for Pneumatic Controls

\*\*\*\*\*

**NOTE: Delete the following paragraph if pneumatic controls are not used.**

\*\*\*\*\*

Provide a pressure gauge at each pneumatic control input and output.

Gauges shall have a 2-inch diameter face and a 0 to 30 psi scale with 1 psi graduations.

## 2.7 PNEUMATIC POWER SUPPLY AND TUBING

\*\*\*\*\*  
NOTE: Delete this paragraph and the following subparagraphs if there are no new pneumatic compressors or control tubing work; otherwise edit accordingly.  
\*\*\*\*\*

### 2.7.1 Air Compressors

\*\*\*\*\*  
NOTE: Indicate new compressed air station locations on the drawings. Locate compressors away from quiet occupied spaces. Mount compressors on concrete housekeeping pads adjacent to a wall and mount dryers on the wall. Provide means of draining the compressed air tank. Provide duplex air compressors for systems having more than 50 control air devices, or requiring more than 1.5 CFM of air. Size duplex air compressors for 50 percent run time, and size single air compressors for 33 percent run time. Show power sources for compressors and dryers.  
\*\*\*\*\*

Air compressors for pneumatic control systems shall be the tank-mounted, electric motor driven, air cooled, reciprocating type with integral [duplex motors and compressors] [single motor and compressor], tank, controller, [alternator switch, ]pressure switch, belt guard[s], pressure relief valve, and automatic moisture drain valve. Compressor piston speeds shall not exceed 450 fpm. Provide compressors with a dry-type combination intake air filter and silencer with baked enamel steel housing. The filter shall be 99 percent efficient at 10 microns. The pressure switch shall start the compressor[s] at 70 psig and stop the compressor[s] at 90 psig. The relief valve shall be set for 10 to 25 psig above the control switch cut-off pressure. Provide compressor capacity suitable for not more than a [33] [50] percent run time, at full system control load. Compressors shall have a maintaining type starter, and shall automatically restart after a power outage. Motors 0.5 hp and larger shall be three-phase.

#### 2.7.1.1 Compressed Air Tank

Provide a steel tank constructed and labeled in agreement with ASME BPVC for 125 psig maximum working pressure. Size the tank for the compressor run time specified above. Provide drain valve and piping routing the drainage to a floor sink or other safe and visible drainage location.

#### 2.7.2 Refrigerated Air Dryers

Provide each air compressor tank with a refrigerant air dryer sized for continuous operation, and capable of reducing the compressed air dew point temperature, at 20 psig output pressure, to 30 degrees F, at an average tank pressure of 80 psig and an ambient air temperature between 55 and 95 degrees F. Provide each dryer with an automatic condensate drain trap with manual override feature. Provide the dryer suction line with a refrigerant pressure gauge. Locate each dryer in the air piping between the tank and

the pressure-reducing station.

#### 2.7.3 Compressed Air Discharge Filters

Provide air compressors with a dry type discharge filter, 99 percent efficient at removing oil and solid particles at 0.03 microns, with baked enamel steel housing and manual drain valve. Provide visual indicator to show when the filter element should be changed.

#### 2.7.4 Air Pressure-Reducing Stations

Provide air compressors with a pressure-reducing valve (PRV) with a field adjustable range of 0 to 50 psig discharge pressure, at an inlet pressure of 70 to 90 psig. Provide a factory-set pressure relief valve downstream of the PRV to relieve over-pressure. Provide a pressure gage upstream of the PRV with range of 0 to 100 psig and downstream of the PRV with range of 0 to 30 psig. For two-pressure control systems, provide an additional PRV and downstream pressure gage.

#### 2.7.5 In-line Filters

Provide a disposable type in-line filter in the incoming pneumatic main at each pneumatic control panel. The filter shall be capable of eliminating 99.99 percent of all liquid or solid contaminants 0.1 micron or larger. Provide the filter with fittings that allow easy removal/replacement.

#### 2.7.6 Pneumatic Tubing

\*\*\*\*\*  
NOTE: Smoke removal and other critical systems  
require non-combustible tubing.  
\*\*\*\*\*

##### 2.7.6.1 Copper Tubing

Provide ASTM B 75 or ASTM B 88M ASTM B 88 rated tubing. Tubing 0.64 mm 0.375 inch outside diameter and larger shall have minimum wall thickness equal to ASTM B 88M ASTM B 88, Type M. Tubing less than 10 mm0.375 inch outside diameter shall have minimum wall thickness of 0.64 mm0.025 inch. Exposed tubing and tubing for working pressures greater than 30 psig shall be hard copper. Fittings shall be ASME B16.18 or ASME B16.22 solder type using ASTM B 32 95-5 tin-antimony solder, or ASME B16.26 compression type.

##### 2.7.6.2 Polyethylene Tubing

Polyethylene tubing may only be used in systems with working pressure of 30 psig or less. Provide flame-resistant, multiple polyethylene tubing in flame-resistant protective sheath with mylar barrier, or unsheathed polyethylene tubing in rigid metal, intermediate metal, or electrical metallic tubing conduit for areas where tubing is exposed. Single, unsheathed, flame-resistant polyethylene tubing may be used where concealed in walls or above ceilings and within control panels. Do not provide polyethylene tubing for [systems indicated as critical and] smoke removal systems. Provide compression or brass barbed push-on type fittings. Extruded seamless polyethylene tubing shall conform to the following:

- a. Minimum Burst Pressure Requirements: 100 psig690 kPa at 75 degrees F24 degrees C to 25 psig172 kPa at 150 degrees F66 degrees C.

- b. Stress Crack Resistance: **ASTM D 1693**, 200 hours minimum.
- c. Tensile Strength (Minimum): **ASTM D 638**, 7583 kPa1100 psi.
- d. Flow Rate (Average): **ASTM D 1238**, 0.30 decigram per minute.
- e. Density (Average): **ASTM D 792**, 920 kg/m<sup>3</sup>57.5 pounds per cubic feet.
- f. Burn rate: **ASTM D 635**

## 2.8 VARIABLE FREQUENCY (MOTOR) DRIVES

\*\*\*\*\*  
**NOTE: Delete the following section if variable frequency motor drives are not used, or are provided under another section.**  
 \*\*\*\*\*

Provide variable frequency drives (VFDs) as indicated. VFDs shall convert 240 or 460 volt (+/- 10%), three phase, 60 hertz (+/- 2Hz), utility grade power to adjustable voltage/frequency, three phase, AC power for stepless motor control from 5% to 105% of base speed. VFDs shall be UL listed as delivered to the end user. The VFD shall meet the requirements specified in the most current National Electrical Code. Each VFD shall also meet the following:

- a. The VFD shall use sine coded Pulse Width Modulation (PWM) technology. PWM calculations shall be performed by the VFD microprocessor.
- b. The VFD shall be capable of automatic control by a remote 4-20 mA [0 to 10 VDC] signal, by network command, or manually by the VFD control panel.

### 2.8.1 VFD Quality Assurance

VFDs shall be the manufacturer's current standard production unit with at least 10 identical units successfully operating in the field.

### 2.8.2 VFD Service Support

- a. Warranty: Provide the VFDs with a minimum 24-month full parts and labor warranty. The warranty shall start when the contract's HVAC system is accepted by the Government. Include warranty documentation, dates, and contact information with the VFD on-site service manuals.
- b. **VFD Service Manuals:** Provide the VFDs with all necessary installation, operation, maintenance, troubleshooting, service, and repair manuals in English including related factory technical bulletins. Provide the documents factory bound, in sturdy 3-ring binders, or hard bound covers. Provide a title sheet on the outside of each binder indicating the project title, project location, installing contractor, contract number, and the VFD manufacturer, address, and telephone number. Each binder shall include a table of contents and tabbed dividers, with all material neatly organized. The documentation provided shall be specifically applicable to this project, shall be annotated to reflect the actual project conditions, and shall provide a

complete and concise depiction of the installed work.[ Provide a storage cabinet on or near the VFD large enough to hold all of the documentation. Have the cabinet's proposed installation site approved in advance by the Contracting Officer. Prominently label the cabinet "VFD OPERATION AND MAINTENANCE MANUALS." Clearly label each manual with the wording "MECHANICAL ROOM COPY - DO NOT REMOVE".]

- c. Technical Support: Provide the VFDs with manufacturer's technical telephone support in English, readily available during normal working hours, and free of charge for the life of the equipment.
- d. Initial Start-Up: Provide the VFDs with factory-trained personnel for the on-site start-up of the HVAC equipment and associated VFD. The personnel shall be competent in the complete start-up, operation, and repair of the particular model VFD installed. The factory start-up representative shall perform the factory's complete recommended start-up procedures and check-out tests on the VFD. Include a copy of the start-up test documentation with the VFD on-site service manuals.
- e. Provide the VFDs with on-site/hands-on training for the user and maintenance personnel. Provide a capable and qualified instructor with minimum two years field experience with the operation and maintenance of similar VFDs. The training shall occur during normal working hours and last not less than 2 hours. Coordinate the training time with the Contracting Officer and the end user. The VFD service manuals shall be used during the training. The contractor shall ensure the manuals are on-site before the start of training. The training shall cover all operational aspects of the VFD.

### 2.8.3 VFD Features

VFDs shall have the following features:

- a. A local operator control keypad capable of:
  - (1) Remote/Local operator selection with password access.
  - (2) Run/Stop and manual speed commands.
  - (3) All programming functions.
  - (4) Scrolling through all display functions.
- b. Digital display capable of indicating:
  - (1) VFD status.
  - (2) Frequency.
  - (3) Motor RPM.
  - (4) Phase current.
  - (5) Fault diagnostics in descriptive text.
  - (6) All programmed parameters.



- c. Standard PI loop controller with input terminal for controlled variable and parameter settings.
- d. User interface terminals for remote control of VFD speed, speed feedback, and an isolated form C SPDT relay, which energizes on a drive fault condition.
- e. An isolated form C SPDT auxiliary relay which energizes on a run command.
- f. A metal NEMA 1 enclosure for indoors, NEMA 4 with heater for outdoors.
- g. An adjustable carrier frequency with 16 KHz minimum upper limit.
- h. A built in or external line reactor with 3% minimum impedance to protect the VFDs DC buss capacitors and rectifier section diodes.

#### 2.8.4 Programmable Parameters

VFDs shall include the following operator programmable parameters:

- a. Upper and lower limit frequency.
- b. Acceleration and Deceleration rate.
- c. Variable torque volts per Hertz curve.
- d. Starting voltage level.
- e. Starting frequency level.
- f. Display speed scaling.
- g. Enable/disable auto-restart feature.
- h. Enable/disable soft stall feature.
- i. Motor overload level.
- j. Motor stall level.
- k. Jump frequency and hysteresis band.
- l. PWM carrier frequency.

#### 2.8.5 Protective Features

VFDs shall have the following protective features:

- a. An electronic adjustable inverse time current limit with consideration for additional heating of the motor at frequencies below 45Hz, for the protection of the motor.
- b. An electronic adjustable soft stall feature, allowing the VFD to lower the frequency to a point where the motor will not exceed the full-load amperage when an overload condition exists at the requested frequency. The VFD will automatically return to the

requested frequency when load conditions permit.

- c. A separate electronic stall at 110% VFD rated current, and a separate hardware trip at 190% current.
- d. Ground fault protection that protects the output cables and motor from grounds during both starting and continuous running conditions.
- e. The ability to restart after the following faults:
  - (1) Overcurrent (drive or motor).
  - (2) Power outage.
  - (3) Phase loss.
  - (4) Over voltage/Under voltage.
- f. The ability shut down if inadvertently started into a rotating load without damaging the VFD or the motor.
- g. The ability to keep a log of a minimum of four previous fault conditions, indicating the fault type and time of occurrence in descriptive text.
- h. The ability to sustain 110% rated current for 60 sec.
- i. The ability to shutdown safely or protect against and record the following fault conditions:
  - (1) Over current (and an indication if the over current was during acceleration, deceleration, or running).
  - (2) Over current internal to the drive.
  - (3) Motor overload at start-up.
  - (4) Over voltage from utility power.
  - (5) Motor running overload.
  - (6) Over voltage during deceleration.
  - (7) VFD over heat.
  - (8) Load end ground fault.
  - (9) Abnormal parameters or data in VFD EEPROM.

#### 2.8.6 Minimum Operating Conditions

VFDs shall be designed and constructed to operate within the following service conditions:

- a. Ambient Temperature Range, 0 to 120 deg. F.
- b. Non-condensing relative humidity to 90%.

### 2.8.7 Additional Features

Provide VFDs with the following additional features:

- [a. BACnet communication interface port]
- [b. RFI/EMI filters]
- [c. Manual bypass circuit and switch integral [external] to the drive to allow drive bypass and operation at 100% speed. Motor overload and short circuit protective features shall remain in use during the bypass mode.]
- [d. One spare VFD of each model provided, fully programmed and ready for back-up operation when connected.]

## PART 3 EXECUTION

### 3.1 INSTALLATION

Perform the installation under the supervision of competent technicians regularly employed in the installation of DDC systems.

\*\*\*\*\*  
NOTE: Provide or coordinate a list of standardized names, BACnet project numbers, device and network addresses, and priority level assignments with the Contractor and BAS Owner early in the project. If no list exists, develop one prior to contract award.  
\*\*\*\*\*

#### 3.1.1 BACnet Naming and Addressing

Coordinate with the BAS Owner and provide unique naming and addressing for BACnet networks and devices.

##### a. MAC Address

Every BACnet device shall have an assigned and documented MAC Address unique to its network. For Ethernet networks, document the MAC Address assigned at its creation. For ARCNET or MS/TP, assign from 00 to 64.

##### b. Network Numbering

Assign unique numbers to each new network installed on the BACnet internetwork. Provide ability for changing the network number; either by device switches, network computer, or field operator interface. The BACnet internetwork (all possible connected networks) can contain up to 65,534 possible unique networks.

##### c. Device Object Identifier Property Number

Assign unique Device "Object\_Identifier" property numbers or device instances for each device on the BACnet internetwork. Provide for future modification of the device instance number; either by device switches, network computer, or field interface. BACnet allows up to 4,194,302 possible unique devices per

internetwork.

d. Device Object Name Property Text

The Device Object Name property field shall support 32 minimum printable characters. Assign unique Device "Object\_Name" property names with plain-English descriptive names for each device. For example, the Device Object Name that for the device controlling the chiller plant at Building 3408 would be:

Device Object\_Name = CW System B3408

A Device Object Name for a VAV box controller might be:

Device Object\_Name = VAV BOX25

e. Object Name Property Text (Other than Device Objects)

The Object Name property field shall support 32 minimum printable characters. Assign Object Name properties with plain-English names descriptive of the application. Examples include "Zone 1 Temperature" and "Fan Start/Stop".

f. Object Identifier Property Number (Other than Device Objects)

Assign Object Identifier property numbers according to design drawings or tables if provided. If not provided, Object Identifier property numbers may be assigned at the Contractor's discretion but must be approved by the Government. In this case they must be documented and unique for like object types within the device.

### 3.1.2 Minimum BACnet Object Requirements

a. Use of Standard BACnet Objects

For the following points and parameters, use standard BACnet objects, where all relevant object properties can be read using BACnet's Read Property Service, and all relevant object properties can be modified using BACnet's Write Property Service: all device physical inputs and outputs, all set points, all PID tuning parameters, all calculated pressures, flow rates, and consumption values, all alarms, all trends, all schedules, and all equipment and lighting circuit operating status.

b. BACnet Object Description Property

The Object Description property shall support 32 minimum printable characters. For each object, complete the description property field using a brief, narrative, plain English description specific to the object and project application. For example: "HW Pump 1 Proof." Document compliance, length restrictions, and whether the description is writeable in the device PICS.

c. Analog Input, Output, and Value Objects

Support and provide Description and/or Device\_Type text strings matching signal type and engineering units shown on the points list.

d. Binary Input, Output, and Value Objects

Support and provide Inactive\_Text and Active\_Text property descriptions matching conditions shown on the points list.

e. Calendar Object

For devices with scheduling capability, provide at least one Calendar Object with ten-entry capacity. All operators may view Calendar Objects; authorized operators may make modifications from a workstation. Enable the writeable Date List property and support all calendar entry data types.

f. Schedule Object

Use Schedule Objects for all building system scheduling. All operators may view schedule entries; authorized operators may modify schedules from a workstation.

g. Loop Object or Equal

Use Loop Objects or equivalent BACnet objects in each applicable field device for PID control. Regardless of program method or object used, allow authorized operators to adjust the Update Interval, Setpoint, Proportional Constant, Integral Constant, and Derivative Constant using BACnet read/write services.

3.1.3 Minimum BACnet Service Requirements

a. Command Priorities

Use commandable BACnet objects to control machinery and systems, providing the priority levels listed below. If the sequence of operation requires a different priority, obtain approval from the Contracting Officer.

<u>Priority Level</u>	<u>Application</u>
1	Manual-Life Safety
2	Automatic-Life Safety
3	(User Defined)
4	(User Defined)
5	Critical Equipment Control
6	Minimum On/Off
7	(User Defined)
8	Manual Operator
9	(User Defined)
10	(User Defined)
11	Load Shedding
12	(User Defined)
13	(User Defined)
14	(User Defined)
15	(User Defined)
16	(User Defined)

b. Alarming

(1) Alarm Priorities - Coordinate alarm and event notification with the BAS Owner.

(2) Notification Class - Enable writeable Priority, Ack Required, and Recipient List properties of Notification Class objects.

(3) Event Notification Message Texts - Use condition specific narrative text and numerical references for alarm and event notification.

c. Updating Displayed Property Values

Allow workstations to display property values at discrete polled intervals, or based on receipt of confirmed and unconfirmed Change of Value notifications. The COV increment shall be adjustable by an operator using BACnet services, and polled intervals shall be adjustable at the operator workstation.

3.1.4 Local Area Networks

Obtain Government approval before connecting new networks with existing networks. Network numbers and device instance numbers shall remain unique when joining networks. Do not change existing network addressing without Government approval. See also "BACnet Naming and Addressing".

3.1.5 BACnet Routers, Bridges, and Switches

Provide the quantity of BACnet routers, bridges, and switches necessary for communications shown on the BACnet Communication Architecture schematic. Provide BACnet routers with BACnet Broadcast Message Device (BBMD) capability on each BACnet internetwork communicating across an IP network. Configure each BACnet device and bridge, router, or switch to communicate on its network segment.

3.1.6 Wiring Criteria

- a. Run circuits operating at more than 100 volts in rigid or flexible conduit, metallic tubing, covered metal raceways, or armored cable.
- b. Do not run binary control circuit wiring in the same conduit as power wiring over 100 volts. Where analog signal wiring requires conduit, do not run in the same conduit with AC power circuits or control circuits operating at more than 100 volts.
- c. Provide circuit and wiring protection required by NFPA 70.
- d. Run all wiring located inside mechanical rooms in conduit.
- e. Do not bury aluminum-sheathed cable or aluminum conduit in concrete.
- f. Input/output identification: Permanently label each field-installed wire, cable, and pneumatic tube at each end with descriptive text using a commercial wire marking system that fully encircles the wire, cable, or tube. Locate the markers within 2 inches of each termination. Match the names and I/O number to the project's point list. Similarly label all power wiring serving control devices, including the word "power" in the label. Number each pneumatic tube every six feet. Label all terminal blocks with alpha/numeric labels. All wiring and the wiring methods

shall be in accordance with UL 508A.

- g. For controller power, provide new 120 VAC circuits, with ground. Provide each circuit with a dedicated breaker, and run wiring in its own conduit, separate from any control wiring. Connect the controller's ground wire to the electrical panel ground; conduit grounds are not acceptable.
- h. Surge Protection: Install surge protection according to manufacturer's instructions. Multiple controllers fed from a common power supply may be protected by a common surge protector, properly sized for the total connected devices.
- i. Grounding: Ground controllers and cabinets to a good earth ground as specified in Section 26 20 00 INTERIOR DISTRIBUTION SYSTEM. Conduit grounding is not acceptable; all grounding shall have a direct path to the building earth ground. Ground sensor drain wire shields at the controller end.
- j. The Contractor shall be responsible for correcting all associated ground loop problems.
- k. Run wiring in panel enclosures in covered wire track.

#### 3.1.7 Accessibility

Install all equipment so that parts requiring periodic inspection, operation, maintenance, and repair are readily accessible. Install digital controllers, data ports, and concealed actuators, valves, dampers, and like equipment in locations freely accessible through access doors.

#### 3.1.8 Digital Controllers

- a. Install as stand alone control devices (see definitions).
- b. Locate control cabinets at the locations shown on the drawings. If not shown on the drawings, install in the most accessible space, close to the controlled equipment.

#### 3.1.9 Hand-Off-Auto Switches

Wire safety controls such as smoke detectors and freeze protection thermostats to protect the equipment during both hand and auto operation.

#### 3.1.10 Temperature Sensors

Install temperature sensors in locations that are accessible and provide a good representation of sensed media. Installations in dead spaces are not acceptable. Calibrate sensors according to manufacturer's instructions. Do not use sensors designed for one application in a different application.

##### 3.1.10.1 Room Temperature Sensors

Mount the sensors on interior walls to sense the average room temperature at the locations indicated. Avoid locations near heat sources such as copy machines or locations by supply air outlet drafts. Mount the center of the sensor [5 feet above the finished floor] [54 inches above the floor to meet ADA requirements] [at the height[s] indicated].

#### 3.1.10.2 Duct Temperature Sensors

- a. Probe Type: Provide a gasket between the sensor housing and the duct wall. Seal the duct penetration air tight. Seal the duct insulation penetration vapor tight.
- b. Averaging Type (and coil freeze protection thermostats): Weave the capillary tube sensing element in a serpentine fashion perpendicular to the flow, across the duct or air handler cross-section, using durable non-metal supports. Prevent contact between the capillary and the duct or air handler internals. Provide a duct access door at the sensor location. The access door shall be hinged on the side, factory insulated, have cam type locks, and be as large as the duct will permit, maximum 18 x 18 inches. For sensors inside air handlers, the sensors shall be fully accessible through the air handler's access doors without removing any of the air handler's internals.

#### 3.1.10.3 Immersion Temperature Sensors

Provide thermowells for sensors measuring piping, tank, or pressure vessel temperatures. Locate wells to sense continuous flow conditions. Do not install wells using extension couplings. Where piping diameters are smaller than the length of the wells, provide wells in piping at elbows to sense flow across entire area of well. Wells shall not restrict flow area to less than 70 percent of pipe area. Increase piping size as required to avoid restriction. Provide thermal conductivity material within the well to fully coat the inserted sensor.

#### 3.1.10.4 Outside Air Temperature Sensors

\*\*\*\*\*  
**NOTE: Show the OA temperature sensor on the north  
side of the building on the drawings.**  
\*\*\*\*\*

Provide outside air temperature sensors in weatherproof enclosures on the north side of the building, away from exhaust hoods and other areas that may affect the reading. Provide a shield to shade the sensor from direct sunlight.

#### 3.1.11 Energy Meters

Locate energy meters as indicated. Connect each meter output to the DDC system, to measure both instantaneous and accumulated energy usage.

#### 3.1.12 Damper Actuators

Where possible, mount actuators outside the air stream in accessible areas.

#### 3.1.13 Thermometers and Gages

Mount devices to allow reading while standing on the floor or ground, as applicable.

#### 3.1.14 Pressure Sensors

Locate pressure sensors as indicated.



#### 3.1.15 Pneumatic Tubing

Run tubing concealed in finished areas, run tubing exposed in unfinished areas like mechanical rooms. For tubing enclosed in concrete, provide rigid metal conduit. Run tubing parallel and perpendicular to building walls. Use 5 foot maximum spacing between tubing supports. With the compressor turned off, test each tubing system pneumatically at 1.5 times the working pressure and prove it air tight, locating and correcting leaks as applicable. Caulking joints is not permitted. Do not run tubing and electrical power conductors in the same conduit.]

#### 3.1.16 Component Identification Labeling

Using an electronic hand-held label maker with white tape and bold black block lettering, provide an identification label on the exterior of each new control panel, control device, actuator, and sensor. Also provide labels on the exterior of each new control actuator indicating the (full) open and (full) closed positions. For labels located outdoors, use exterior grade label tape, and provide labels on both the inside and outside of the panel door or device cover. Acceptable alternatives are white plastic labels with engraved bold black block lettering permanently attached to the control panel, control device, actuator, and sensor. Have the labels and wording approved by the BAS Owner prior to installation.

#### 3.1.17 Network and Telephone Communication Lines

When telephone lines or network connections by the Government are required, provide the Contracting Officer at least 60 days advance notice of need.

### 3.2 TEST AND BALANCE SUPPORT

The controls contractor shall coordinate with and provide on-site support to the test and balance (TAB) personnel [specified under Section 23 08 00.00 20 HVAC TESTING/ADJUSTING/BALANCING.] This support shall include:

- a. On-site operation and manipulation of control systems during the testing and balancing.
- b. Control setpoint adjustments for balancing all relevant mechanical systems, including VAV boxes.
- c. Tuning control loops with setpoints and adjustments determined by TAB personnel.

### 3.3 CONTROLS SYSTEM OPERATORS MANUALS

Provide two [three] [four] electronic and printed copies of a Controls System Operators Manual. The manual shall be specific to the project, written to actual project conditions, and provide a complete and concise depiction of the installed work. Provide information in detail to clearly explain all operation requirements for the control system.

Provide with each manual: CDs of the project's control system drawings, control programs, data bases, graphics, and all items listed below. Include gateway back-up data and configuration tools where applicable. Provide CDs in jewel case with printed and dated project-specific labels on both the CD and the case. For text and drawings, use Adobe Acrobat or MS Office file types. When approved by the Government, AutoCAD and Visio

files are allowed. Give files descriptive English names and organize in folders.

Provide printed manuals in sturdy 3-ring binders with a title sheet on the outside of each binder indicating the project title, project location, contract number, and the controls contractor name, address, and telephone number. Each binder shall include a table of contents and tabbed dividers, with all material neatly organized. Manuals shall include the following:

- a. A copy of the as-built control system (shop) drawings set, with all items specified under the paragraph "Submittals." Indicate all field changes and modifications.
- b. A copy of the project's mechanical design drawings, including any official modifications and revisions.
- c. A copy of the project's approved Product Data submittals provided under the paragraph "Submittals."
- d. A copy of the project's approved Performance Verification Testing Plan and Report.
- e. A copy of the project's approved final TAB Report.
- f. Printouts of all control system programs, including controller setup pages if used. Include plain-English narratives of application programs, flowcharts, and source code.
- g. Printouts of all physical input and output object properties, including tuning values, alarm limits, calibration factors, and set points.
- h. A table entitled "AC Power Table" listing the electrical power source for each controller. Include the building electrical panel number, panel location, and circuit breaker number.
- i. The DDC manufacturer's hardware and software manuals in both print and CD format with printed project-specific labels. Include installation and technical manuals for all controller hardware, operator manuals for all controllers, programming manuals for all controllers, operator manuals for all workstation software, installation and technical manuals for the workstation and notebook, and programming manuals for the workstation and notebook software.
- j. A list of qualified control system service organizations for the work provided under this contract. Include their addresses and telephone numbers.
- k. A written statement entitled "Technical Support" stating the control system manufacturer or authorized representative will provide toll-free telephone technical support at no additional cost to the Government for a minimum of two years from project acceptance, will be furnished by experienced service technicians, and will be available during normal weekday working hours. Include the toll-free technical support telephone number.
- l. A written statement entitled "Software Upgrades" stating software and firmware patches and updates will be provided upon request at

no additional cost to the Government for a minimum of two years from contract acceptance. Include a table of all DDC system software and firmware provided under this contract, listing the original release dates, version numbers, part numbers, and serial numbers.

#### [3.3.1 Storage Cabinets

In each project mechanical room, provide a wall-mounted metal storage cabinet with hinged doors. In addition to the number of manuals specified above, provide an additional copy of the manuals in each of these mechanical room storage cabinets. Provide cabinets large enough to hold the entire set of Controls System Operators Manuals, and the HVAC operation and maintenance manuals [provided under Division 15 MECHANICAL.] Locate cabinets adjacent to DDC control panels where applicable. Have each cabinet's proposed installation site approved in advance by the Contracting Officer and the BAS Owner. Prominently label each cabinet with the wording "OPERATION AND MAINTENANCE MANUALS." Prominently label each binder with the wording "MECHANICAL ROOM COPY - DO NOT REMOVE."]

### 3.4 PERFORMANCE VERIFICATION TESTING (PVT)

#### 3.4.1 General

The PVT shall demonstrate compliance of the control system work with the contract requirements. The PVT shall be performed by the Contractor and witnessed and approved by the Government. If the project is phased, provide separate testing for each phase. A Pre-PVT meeting to review the [Pre-PVT Checklist](#) is required to coordinate all aspects of the PVT and shall include the Contractor's QA representative, the Contractor's PVT administrator, the Contracting Officer's representative, [ and the BAS Owner].

#### 3.4.2 [Performance Verification Testing Plan](#)

\*\*\*\*\*  
**NOTE: If possible, give the Contractor early guidance and examples for creation and content of PVT procedures and reporting forms.**  
\*\*\*\*\*

Submit a detailed PVT Plan of the proposed testing for Government approval. Develop the PVT Plan specifically for the control system in this contract. The PVT Plan shall be a clear list of test items arranged in a logical sequence. Include the intended test procedure, the expected response, and the pass/fail criteria for every component tested.

The plan shall clearly describe how each item is tested, indicate where assisting personnel are required (like the mechanical contractor), and include what procedures are used to simulate conditions. Include a separate column for each checked item and extra space for comments. Where sequences of operations are checked, insert each corresponding routine from the project's sequence of operation. For each test area, include signature and date lines for the Contractor's PVT administrator, the Contractor's QA representative, the Contracting Officer's representative, [ and the BAS Owner] to acknowledge successful completion. [The BAS Owner can provide sample PVT forms and procedures upon request.]

#### 3.4.3 PVT Sample Size

Test all central plant equipment and primary air handling unit controllers unless otherwise directed. Twenty percent sample testing is allowed for identical controllers typical of terminal control like VAV boxes and fan coil units. The Government may require testing of like controllers beyond a statistical sample if sample controllers require retesting or do not have consistent results.

The Government may witness all testing, or random samples of PVT items. When only random samples are witnessed, the Government may choose which ones.

#### 3.4.4 Pre-Performance Verification Testing Checklist

Submit the following as a list with items checked off once verified. Provide a detailed explanation for any items that are not completed or verified.

- a. Verify all required mechanical installation work is successfully completed, and all HVAC equipment is working correctly (or will be by the time the PVT is conducted).
- b. Verify HVAC motors operate below full-load amperage ratings.
- c. Verify all required control system components, wiring, and accessories are installed.
- d. Verify the installed control system architecture matches approved drawings.
- e. Verify all control circuits operate at the proper voltage and are free from grounds or faults.
- f. Verify all required surge protection is installed.
- g. Verify the A/C Power Table specified in "CONTROLS SYSTEM OPERATORS MANUALS" is accurate.
- h. Verify all DDC network communications function properly, including uploading and downloading programming changes.
- i. Using the BACnet protocol analyzer (if provided or required in this specification), verify communications are error free.
- j. Verify each digital controller's programming is backed up.
- k. Verify all wiring, components, and panels are properly labeled.
- l. Verify all required points are programmed into devices.
- m. Verify all TAB work affecting controls is complete.
- n. Verify all valve and actuator zero and span adjustments are set properly.
- o. Verify all sensor readings are accurate and calibrated.
- p. Verify each control valve and actuator goes to normal position

upon loss of power.

- q. Verify all control loops are tuned for smooth and stable operation. View trend data where applicable.
- r. Verify each controller works properly in stand-alone mode.
- s. Verify all safety controls and devices function properly, including freeze protection and interfaces with building fire alarm systems.
- t. Verify all electrical interlocks work properly.
- u. Verify all workstations, notebooks and maintenance personnel interface tools are delivered, all system and database software is installed, and graphic pages are created for each workstation and notebook.
- v. Verify the as-built (shop) control drawings are completed.

#### 3.4.5 Conducting Performance Verification Testing

- a. Conduct Government-witnessed PVT after approval of the PVT Plan and the completed Pre-PVT Checklist. Notify the Contracting Officer of the planned PVT at least 15 days prior to testing. Provide an estimated time table required to perform the testing. Furnish personnel, equipment, instrumentation, and supplies necessary to perform all aspects of the PVT. Ensure that testing personnel are regularly employed in the testing and calibration of DDC systems. Using the project's as-built control system (shop) drawings, the project's mechanical design drawings, the approved Pre-PVT Checklist, and the approved PVT Plan, conduct the PVT.
- b. During testing, identify any items that do not meet the contract requirements and if time permits, conduct immediate repairs and re-test. Otherwise, deficiencies shall be investigated, corrected, and re-tested later. Document each deficiency and corrective action taken.
- c. If re-testing is required, follow the procedures for the initial PVT. The Government may require re-testing of any control system components affected by the original failed test.

#### 3.4.6 Controller Capability and Labeling

Test the following for each controller:

- a. Memory: Demonstrate that programmed data, parameters, and trend/ alarm history collected during normal operation is not lost during power failure.
- b. Direct Connect Interface: Demonstrate the ability to connect directly to each type of digital controller with a portable electronic device like a notebook computer or PDA. Show that maintenance personnel interface tools perform as specified in the manufacturer's technical literature.
- c. Stand Alone Ability: Demonstrate controllers provide stable and reliable stand-alone operation using default values or other

method for values normally read over the network.

- d. Wiring and AC Power: Demonstrate the ability to disconnect any controller safely from its power source using the AC Power Table. Demonstrate the ability to match wiring labels easily with the control drawings. Demonstrate the ability to locate a controller's location using the BACnet Communication Architecture Schematic and floor plans.
- e. Nameplates and Tags: Show the nameplates and tags are accurate and permanently attached to control panel doors, devices, sensors, and actuators.

#### 3.4.7 Workstation and Software Operation

For every user workstation or notebook provided:

- a. Show points lists agree with naming conventions.
- b. Show that graphics are complete.
- c. Show the UPS operates as specified.

#### 3.4.8 BACnet Communications and Interoperability Areas

Demonstrate proper interoperability of data sharing, alarm and event management, trending, scheduling, and device and network management. If available or required in this specification, use a BACnet protocol analyzer to assist with identifying devices, viewing network traffic, and verifying interoperability. These requirements must be met even if there is only one manufacturer of equipment installed. Testing includes the following:

- a. Data Presentation: On each BACnet Operator Workstation, demonstrate graphic display capabilities.
- b. Reading of Any Property: Demonstrate the ability to read and display any used readable object property of any device on the network.
- c. Setpoint and Parameter Modifications: Show the ability to modify all setpoints and tuning parameters in the sequence of control or listed on project schedules. Modifications are made with BACnet messages and write services initiated by an operator using workstation graphics, or by completing a field in a menu with instructional text.
- d. Peer-to-Peer Data Exchange: Show all BACnet devices are installed and configured to perform BACnet read/write services directly (without the need for operator or workstation intervention), to implement the project sequence of operation, and to share global data.
- e. Alarm and Event Management: Show that alarms/events are installed and prioritized according to the BAS Owner. Demonstrate time delays and other logic is set up to avoid nuisance tripping, e.g., no status alarms during unoccupied times or high supply air during cold morning start-up. Show that operators with sufficient privilege can read and write alarm/event parameters for all standard BACnet event types. Show that operators with sufficient

privilege can change routing (BACnet notification classes) for each alarm/event including the destination, priority, day of week, time of day, and the type of transition involved (TO-OFF NORMAL, TO-NORMAL, etc.).

- f. Schedule Lists: Show that schedules are configured for start/stop, mode change, occupant overrides, and night setback as defined in the sequence of operations.
- g. Schedule Display and Modification: Show the ability to display any schedule with start and stop times for the calendar year. Show that all calendar entries and schedules are modifiable from any connected workstation by an operator with sufficient privilege.
- h. Archival Storage of Data: Show that data archiving is handled by the operator workstation/server, and local trend archiving and display is accomplished with BACnet Trend Log objects.
- i. Modification of Trend Log Object Parameters: Show that an operator with sufficient privilege can change the logged data points, sampling rate, and trend duration.
- j. Device and Network Management: Show the following capabilities -
  - (1) Display of Device Status Information
  - (2) Display of BACnet Object Information
  - (3) Silencing Devices that are Transmitting Erroneous Data
  - (4) Time Synchronization
  - (5) Remote Device Reinitialization
  - (6) Backup and Restore Device Programming and Master Database(s)
  - (7) Configuration Management of Half-Routers, Routers and BBMDs

#### 3.4.9 Execution of Sequence of Operation

Demonstrate that the HVAC system operates properly through the complete sequence of operation. Use read/write property services to globally read and modify parameters over the internetwork.

#### 3.4.10 Control Loop Stability and Accuracy

For all control loops tested, give the Government trend graphs of the control variable over time, demonstrating that the control loop responds to a 20% sudden change of the control variable set point without excessive overshoot and undershoot. If the process does not allow a 20% set point change, use the largest change possible. Show that once the new set point is reached, it is stable and maintained. Control loop trend data shall be in real-time with the time between data points 30 seconds or less.

#### 3.4.11 Performance Verification Testing Report

Upon successful completion of the PVT, submit a PVT Report to the Government and prior to the Government taking use and possession of the facility. Do not submit the report until all problems are corrected and

successfully re-tested. The report shall include the annotated PVT Plan used during the PVT. Where problems were identified, explain each problem and the corrective action taken. Include a written certification that the installation and testing of the control system is complete and meets all of the contract's requirements.

### 3.5 TRAINING REQUIREMENTS

Provide a qualified instructor (or instructors) with two years minimum field experience with the installation and programming of similar BACnet DDC systems. Orient training to the specific systems installed. Coordinate training times with the Contracting Officer and BAS Owner after receiving approval of the training course documentation. Training shall take place at the job site and/or a nearby Government-furnished location. A training day shall occur during normal working hours, last no longer than 8 hours and include a one-hour break for lunch and two additional 15-minute breaks. The project's approved Controls System Operators Manual shall be used as the training text. The Contractor shall ensure the manuals are submitted, approved, and available to hand out to the trainees before the start of training.

#### 3.5.1 Training Documentation

Submit training documentation for review 30 days minimum before training. Documentation shall include an agenda for each training day, objectives, a synopsis of each lesson, and the instructor's background and qualifications. The training documentation can be submitted at the same time as the project's Controls System Operators Manual.

#### 3.5.2 Phase I Training - Fundamentals

The Phase I training session shall last [one day] [two consecutive days] and be conducted in a classroom environment with complete audio-visual aids provided by the contractor. Provide each trainee a printed 8.5 x 11 inch hard-copy of all visual aids used. Upon completion of the Phase I Training, each trainee should fully understand the project's DDC system fundamentals. The training session shall include the following:

- a. BACnet fundamentals (objects, services, addressing) and how/where they are used on this project
- b. This project's list of control system components
- c. This project's list of points and objects
- d. This project's device and network communication architecture
- e. This project's sequences of control, and:
- f. Alarm capabilities
- g. Trending capabilities
- h. Troubleshooting communication errors
- i. Troubleshooting hardware errors



### 3.5.3 Phase II Training - Operation

Provide Phase II Training shortly after completing Phase I Training. The Phase II training session shall last [one day] [two consecutive days] and be conducted at the DDC system workstation, at a notebook computer connected to the DDC system in the field, and at other site locations as necessary. Upon completion of the Phase II Training, each trainee should fully understand the project's DDC system operation. The training session shall include the following:

- a. A walk-through tour of the mechanical system and the installed DDC components (controllers, valves, dampers, surge protection, switches, thermostats, sensors, etc.)
- b. A discussion of the components and functions at each DDC panel
- c. Logging-in and navigating at each operator interface type
- d. Using each operator interface to find, read, and write to specific controllers and objects
- e. Modifying and downloading control program changes
- f. Modifying setpoints
- g. Creating, editing, and viewing trends
- h. Creating, editing, and viewing alarms
- i. Creating, editing, and viewing operating schedules and schedule objects
- j. Backing-up and restoring programming and data bases
- k. Modifying graphic text, backgrounds, dynamic data displays, and links to other graphics
- l. Creating new graphics and adding new dynamic data displays and links
- m. Alarm and Event management
- n. Adding and removing network devices

-- End of Section --